

# CS578- SPEECH SIGNAL PROCESSING

## LECTURE 3: ACOUSTICS OF SPEECH PRODUCTION

Yannis Stylianou



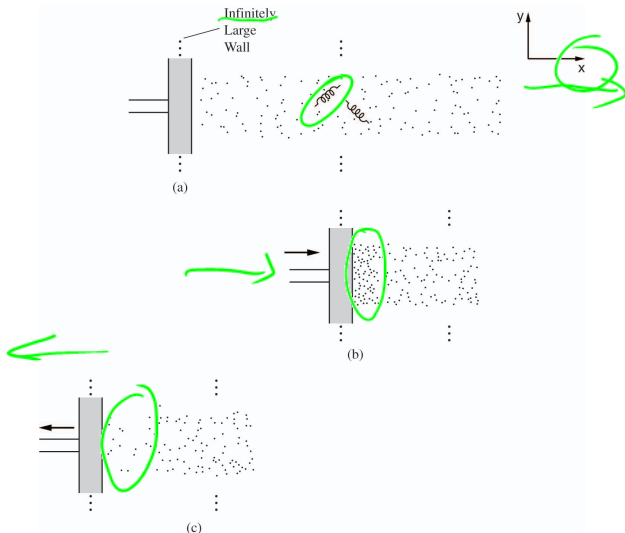
University of Crete, Computer Science Dept., Multimedia Informatics Lab  
yannis@csd.uoc.gr

Univ. of Crete

# OUTLINE

- 1 PHYSICS OF SOUND
- 2 UNIFORM TUBE MODEL
- 3 CONCATENATING N UNIFORM TUBES
- 4 GLOTTAL FLOW DERIVATIVE
- 5 VOCAL FOLD/VOCAL TRACT INTERACTION
- 6 ACKNOWLEDGMENTS
- 7 REFERENCES

# COMPRESSION AND RAREFACTION OF AIR PARTICLES



# SOME DEFINITIONS

- **Sound wave:** propagation of disturbance (local changes in pressure, displacement, and velocity) of particles through a medium, creating the effect of compression or rarefaction.
- **Wavelength:** distance between two consecutive peak compressions,  $\lambda$
- **Frequency:** number of cycles of compressions per second,  $f$
- **Speed of sound:**  $c = f\lambda$  (at sea level and at  $70^\circ F$ ,  $c = 344m/sec$ )
- **Isothermal process:** a slow variation of pressure where the temperature in the medium remains constant
- **Adiabatic process:** a fast variation of pressure where the temperature in the medium increases

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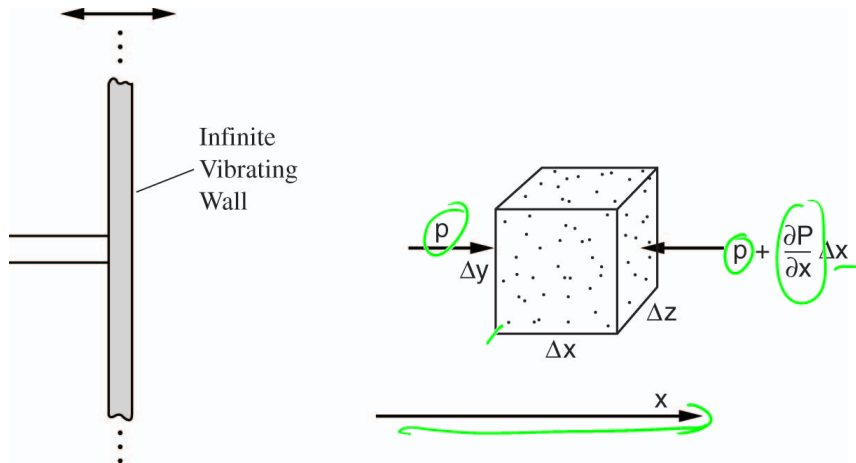
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*QW in*

# CUBE CONFIGURATION



# NOTATION

Assuming *planar propagation*, and within the cube:

- $p(x, t)$  fluctuation of pressure about an ambient or average pressure  $P_0$ .
  - ▷ Threshold of hearing:  $2 \cdot 10^{-5}$  newtons/m<sup>2</sup>
  - ▷ Threshold of pain: 20 newtons/m<sup>2</sup>
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# THE WAVE EQUATION

Under the assumptions:

- If there is no friction of air particles in the cube with those outside the cube (no *viscosity*),
- Cube is very small,
- The density of air particles is constant in the cube (i.e.,  $\rho_0 = \rho$ )

then, one form of the *Wave Equation* is given by:

$$\begin{aligned} -\frac{\partial p}{\partial x} &= \rho \frac{\partial v}{\partial t} \\ -\frac{\partial p}{\partial t} &= \rho c^2 \frac{\partial v}{\partial x} \end{aligned}$$

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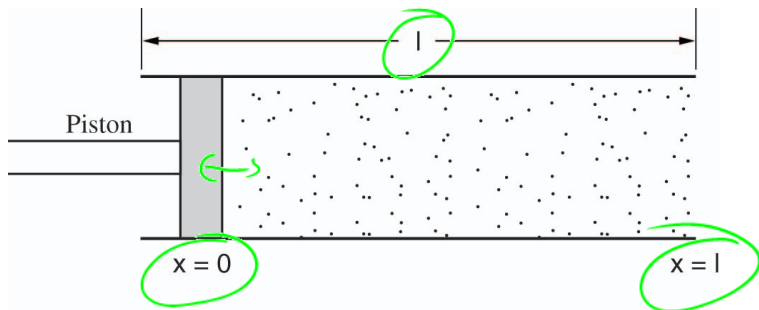
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$$\left| \begin{array}{l} p(x, t) \\ u(x, t) \end{array} \right.$$

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# LOSSLESS CASE OF CROSS SECTION A



$$\begin{aligned} -\frac{\partial p}{\partial x} &= \frac{\rho}{A} \frac{\partial u}{\partial t} \\ -\frac{\partial p}{\partial t} &= \frac{\rho c^2}{A} \frac{\partial u}{\partial x} \end{aligned}$$

where  $u(x, t) = Av(x, t)$

# SOLUTION FOR A LOSSLESS TUBE

Under the assumptions/conditions:

- No friction along the walls of the tube
- At the open end of the tube, there are no variations in air pressure, i.e.  $p(l, t) = 0$
- Volume velocity at  $x = 0$ :  $u(0, t) = U_g(\Omega)e^{j\Omega t}$

▷ Volume velocity:

$$u(x, t) = \frac{\cos[\Omega(l-x)/c]}{\cos(\Omega l/c)} U_g(\Omega)e^{j\Omega t}$$


▷ (Incremental) Pressure:

$$p(x, t) = j \frac{\rho c}{A} \frac{\sin[\Omega(l-x)/c]}{\cos(\Omega l/c)} U_g(\Omega)e^{j\Omega t}$$

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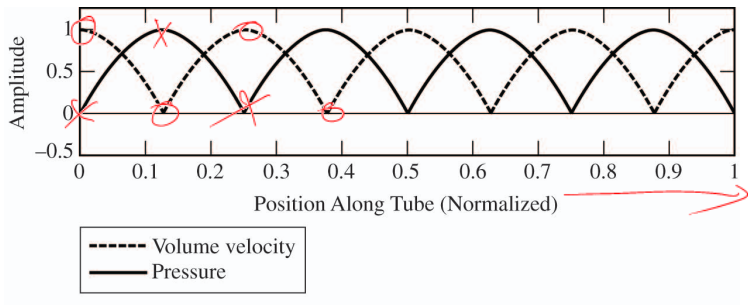
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# VELOCITY AND PRESSURE ARE “ORTHOGONAL”



# INPUT/OUTPUT VOLUME VELOCITY

At  $x = l$

$$u(l, t) = \frac{1}{\cos(\Omega l/c)} U_g(\Omega) e^{j\Omega t}$$

Then, the frequency response  $V(\Omega)$  is:

$$V(\Omega) = \frac{U(l, \Omega)}{U_g(\Omega)} = \frac{1}{\cos(\Omega l/c)}$$

providing resonances of infinite amplitudes at frequencies:

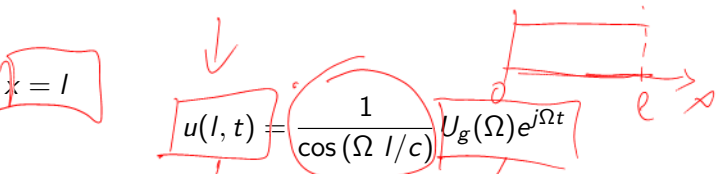
$$\Omega_k = (2k + 1) \frac{\pi c}{2l}, \quad k = 0, 1, 2, \dots$$

Example: if  $l = 35\text{cm}$ ,  $c = 350\text{ m/s}$ , then  $f_k = 250, 750, 1250, \dots$  Hz.



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$$X(z) \rightarrow [H(z)] \rightarrow Y(z)$$

$$Y(z) = H(z) \cdot X(z) \Rightarrow H(z) = \frac{Y(z)}{X(z)}$$

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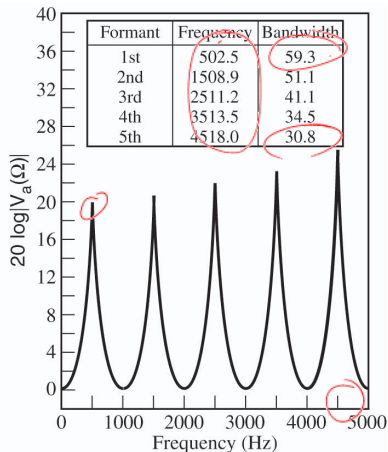
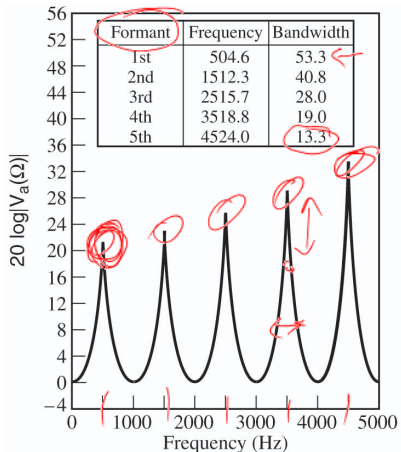
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# UNIFORM TUBE: BEING REALISTIC

Energy loss due to the wall vibration (left) and with viscous and thermal loss (right)[1]:

AB



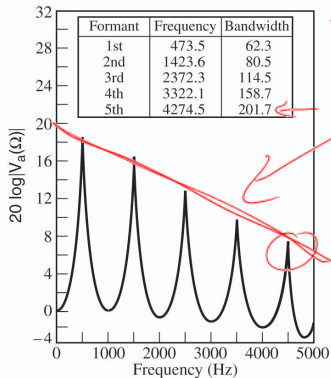
# UNIFORM TUBE: BEING MORE REALISTIC

Sound radiation at the lips, as an acoustic impedance:

$$Z_r(\Omega) = \frac{P(l, \Omega)}{U(l, \Omega)}$$



All the previous losses, plus radiation loss[1]:

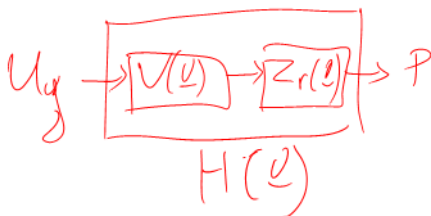


# PRESSURE-TO-VOLUME VELOCITY FREQUENCY RESPONSE

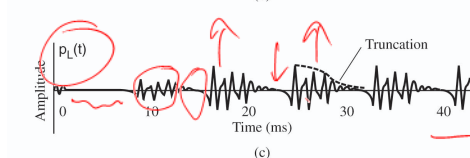
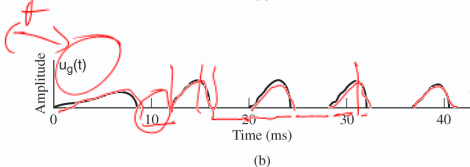
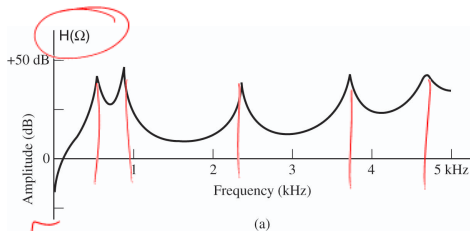
Since we measure pressure at the lips:

$$H(\Omega) = \frac{P(l, \Omega)}{U_g(\Omega)} = \underbrace{Z_r(\Omega)} \underbrace{V(\Omega)}$$

$$Z = \frac{P \leftarrow \text{έξοδος}}{U \leftarrow \text{είσοδος}}$$
$$V = \frac{U \leftarrow \text{έξοδος}}{U_g \leftarrow \text{είσοδος}}$$



# NUMERICAL SIMULATIONS FOR /o/[1]

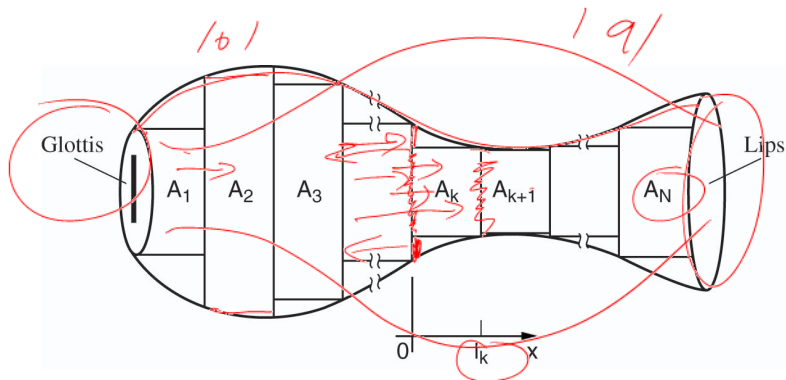


$U_g(\omega)$

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# CONCATENATING LOSSLESS UNIFORM TUBES



Reflection coefficient:

$$r_k = \frac{A_{k+1} - A_k}{A_{k+1} + A_k}$$

# DISCRETIZING THE CONTINUOUS-SPACE TUBE

- Impulse response of  $N$  lossless concatenated tubes with total length  $l$ :

$$h(t) = b_0\delta(t - N\tau) + \sum_{k=1}^{\infty} b_k\delta(t - N\tau - k2\tau)$$

where  $\tau = \frac{\Delta x}{c}$  and  $\Delta x = \frac{l}{N}$

- Frequency response:

$$H(\Omega) = \sum_{k=0}^{\infty} b_k e^{-j\Omega 2k\tau}$$

- Observe that:

$$H\left(\Omega + \frac{2\pi}{2\tau}\right) = H(\Omega)$$



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$\delta(t)$   $\rightarrow$   $\delta(t)$   $\rightarrow$   $h(t)$

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$\delta(t) \rightarrow e^{-j\omega t}$

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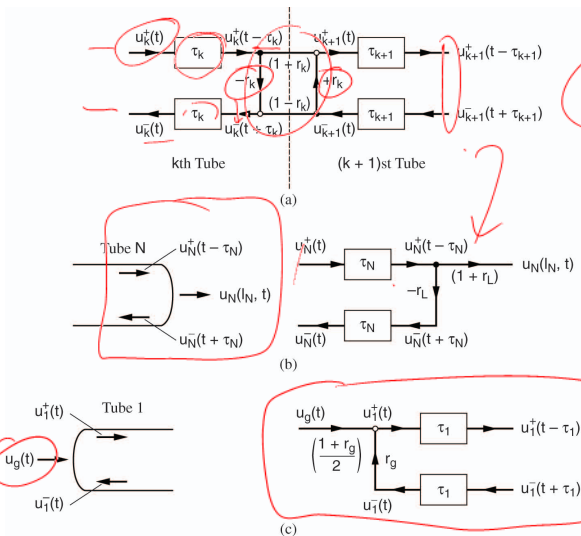
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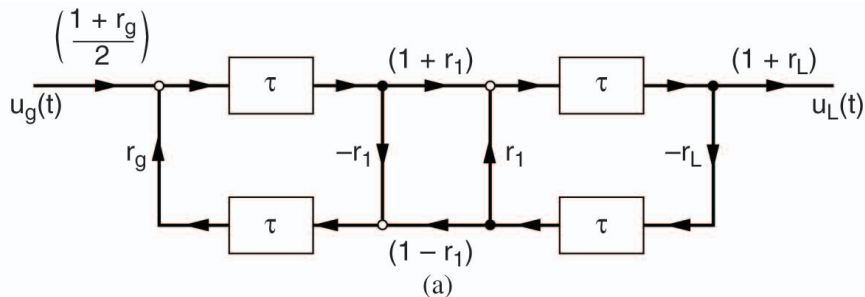
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# SIGNAL FLOW GRAPHS



(a) two concatenated tubes, (b) lip boundary condition, (c) glottal boundary condition

# FOR A LOSSLESS TWO-TUBE MODEL



Transfer function relating the volume velocity at the lips to the glottis:

$$V(s) = \frac{b e^{-s2\tau}}{1 + a_1 e^{-s2\tau} + a_2 e^{-s4\tau}}$$

Laplace  
 $s = \sigma + j\omega$

with  $a_1 = r_1 r_g + r_1 r_L$ ,  $a_2 = r_L r_g$  and  $b = 0.5(1 + r_g)(1 + r_L)(1 + r_1)$   
 (Show me this)

- **Two cubes:** By setting  $z = e^{s2\tau}$ , then:

$$V(z) = \frac{bz^{-1}}{1 + a_1z^{-1} + a_2z^{-2}}$$

- **N cubes:**

$$V(z) = \frac{Az^{-N/2}}{1 + \sum_{k=1}^N a_k z^{-k}}$$

# DISCRETE-TIME LOSSLESS MODELS

$$S \rightarrow Z \quad z^{-k} X(z) \xrightarrow{Z^{-1}} x[n-k]$$

- **Two cubes:** By setting  $z = e^{s2\tau}$ , then:

$$V(z) = \frac{bz^{-1}}{1 + a_1z^{-1} + a_2z^{-2}}$$

$$N=2$$

- **N cubes:**

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$$u_g(z) \rightarrow u(z) \quad z \rightarrow P(z)$$

# CHOOSING THE NUMBER OF TUBE ELEMENTS

## Question:

If a vocal tract has length  $l = 17.5 \text{ cm}$  and the speed of sound  $c = 350 \text{ m/s}$ , how many tubes,  $N$ , do we need to cover a bandwidth of  $5000 \text{ Hz}$ ?

Answer:  $N = 10$

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# COMPLETE DISCRETE-TIME MODEL FROM N TUBES

Discrete-time pressure-to-volume velocity frequency response:

$$H(z) = R(z)V(Z)$$

where  $R(z) \approx 1 - \alpha z^{-1}$  and  $V(z)$  is an all-pole model.  
And for the speech signal (voiced case):

$$X(z) = A_v G(z)H(z)$$

with  $A_v$  to control loudness and  $G(z)$  being the z-transform of the glottal flow input.

or

$$X(z) = A_v G(z) \frac{1 - \alpha z^{-1}}{1 + \sum_{k=1}^N a_k z^{-k}}$$

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# GLOTTAL WAVEFORM MODEL

A typical glottal flow waveform over one cycle is modeled as:

$$g[n] = (b^{-n}u[-n]) \star (b^{-n}u[-n])$$

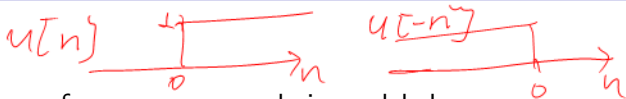
which has as z-transform:

$$G(z) = \frac{1}{(1 - \beta z)^2}$$

So for a *voiced* frame:

$$X(z) = A_v \frac{(1 - az^{-1})}{(1 - bz)^2 (1 + \sum_{k=1}^N a_k z^{-k})}$$

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$$A_v G(z) \cdot \frac{R(z)}{V(z)}$$

# MODELING OTHER STATES

- **For noisy inputs:**

$$X(z) = A_n U(z) V(z) R(z)$$

- **For impulsive sounds:**

$$X(z) = A_i V(z) R(z)$$

- **being more general:**

$$X(z) = A \frac{(1 - az^{-1}) \prod_{k=1}^{M_i} (1 - c_k z^{-1}) \prod_{k=1}^{M_o} (1 - d_k z)}{(1 - bz)^2 (1 - \sum_{k=1}^N a_k z^{-k})}$$

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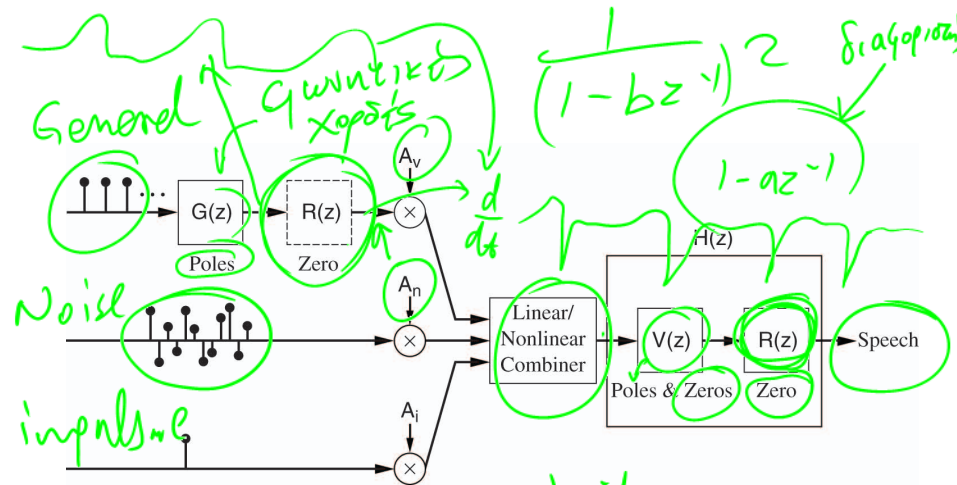
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$$= A_i \frac{1}{(1 - bz)^2} \frac{1 - az^{-1}}{1 + \sum_k d_k z^{-k}}$$

# AN OVERVIEW THEN



$$X(z) \cdot (1-az^{-1})z^{-1} \rightarrow x[n] - ax[n-1]$$

$$X(z)(1-z^{-1})z^{-1} \rightarrow x[n] - x[n-1]$$

$\frac{dx}{dt}$



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- 5 VOCAL FOLD/VOCAL TRACT INTERACTION
- 6 ACKNOWLEDGMENTS
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# GLOTTAL FLOW DERIVATIVE

Since speech signals,  $x(t)$  can be obtained in general by:

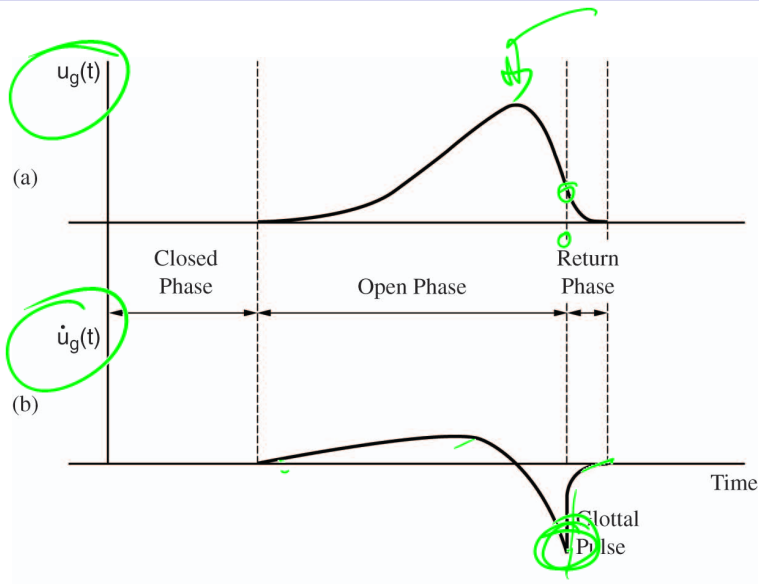
$$x(t) \approx A \frac{d}{dt} [u_g(t) \star v(t)]$$

and because:

$$A \frac{d}{dt} [u_g(t) \star v(t)] = A \left[ \frac{d}{dt} u_g(t) \right] \star v(t)$$

we usually consider the derivative  $\frac{d}{dt} u_g(t)$  as input to the system, which is referred to as *Glottal Flow Derivative*

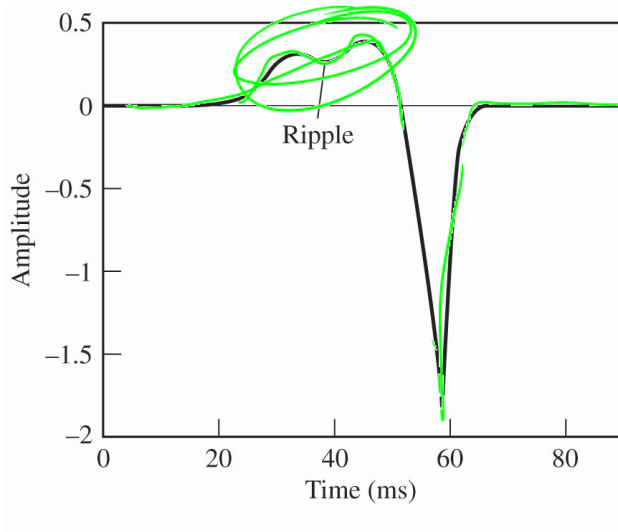
# GLOTTAL FLOW AND ITS DERIVATIVE



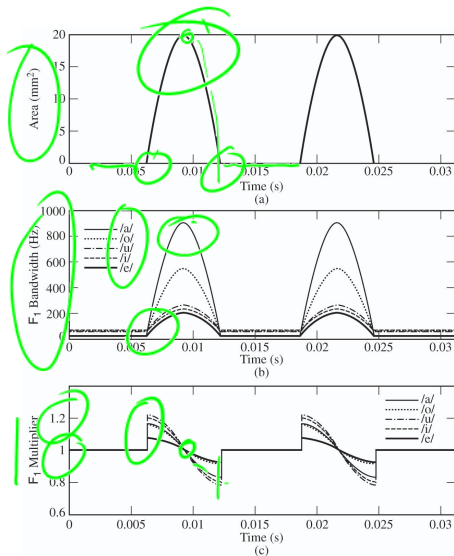
# OUTLINE

- 1 PHYSICS OF SOUND
- 2 UNIFORM TUBE MODEL
- 3 CONCATENATING N UNIFORM TUBES
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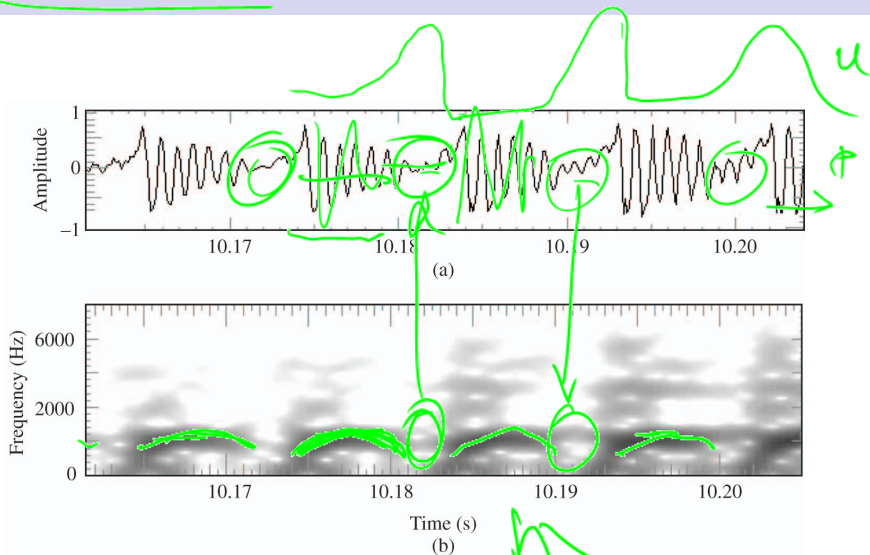
# RIPPLE IN THE GLOTTAL FLOW DERIVATIVE?



# REGARDING THE FIRST FORMANT [2]



# TRUNCATION EFFECT - AGAIN



# OUTLINE

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# ACKNOWLEDGMENTS

Most, if not all, figures in this lecture are coming from the book:

**T. F. Quatieri:** Discrete-Time Speech Signal Processing,  
principles and practice  
2002, Prentice Hall

and have been used after permission from Prentice Hall

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M. Portnoff, *A Quasi-One-Dimensional Digital Simulation for the Time-Varying Vocal Tract*.  
PhD thesis, Massachusetts Institute of Technology, May 1973.



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PhD thesis, Massachusetts Institute of Technology, Dept. of EE and CS, June 1996.

