

CS578- SPEECH SIGNAL PROCESSING

LECTURE 7: SPEECH CODING

Yannis Stylianou



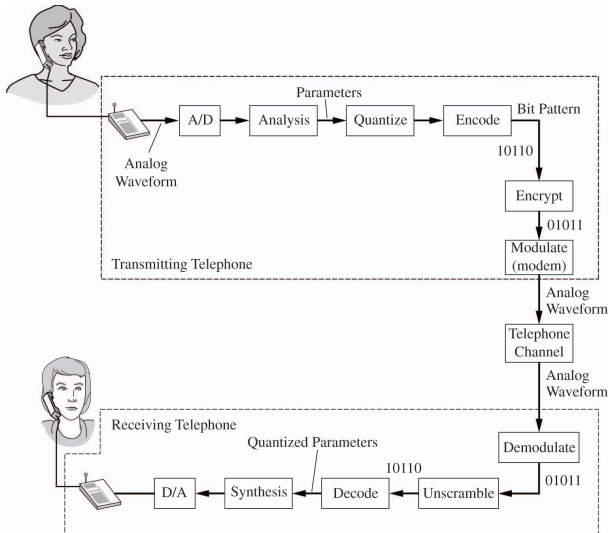
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Univ. of Crete

OUTLINE

- 1 INTRODUCTION
- 2 STATISTICAL MODELS
- 3 SCALAR QUANTIZATION
 - Max Quantizer
 - Companding
 - Adaptive quantization
 - Differential and Residual quantization
- 4 VECTOR QUANTIZATION
 - The k-means algorithm
 - The LBG algorithm
- 5 MODEL-BASED CODING
 - Basic Linear Prediction, LPC
 - Mixed Excitation LPC (MELP)
- 6 ACKNOWLEDGMENTS

DIGITAL TELEPHONE COMMUNICATION SYSTEM



CATEGORIES OF SPEECH CODERS

- Waveform coders (16-64 kbps, $f_s = 8000\text{Hz}$)
- Hybrid coders (2.4-16 kbps, $f_s = 8000\text{Hz}$)
- Vocoders (1.2-4.8 kbps, $f_s = 8000\text{Hz}$)

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- Naturalness
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- Intelligibility
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MEASURING SPEECH QUALITY

▷ Subjective tests:

- Diagnostic Rhyme Test (DRT)
- Diagnostic Acceptability Measure (DAM)
- Mean Opinion Score (MOS)

▷ Objective tests:

- Segmental Signal-to-Noise Ratio (SNR)
- Articulation Index

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PROBABILITY DENSITY OF SPEECH

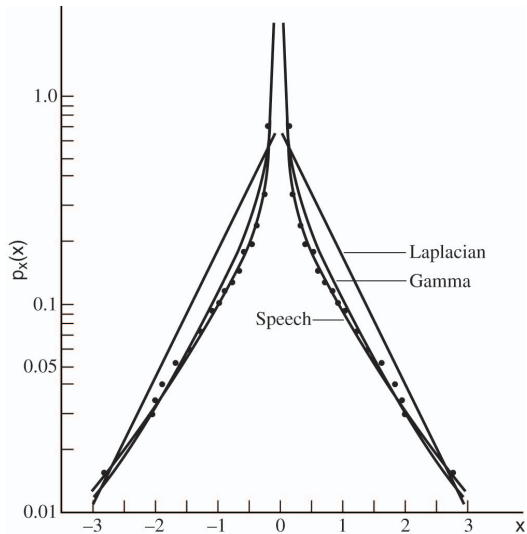
By setting $x[n] \rightarrow x$, the histogram of speech samples can be approximated by a *gamma density*:

$$p_X(x) = \left(\frac{\sqrt{3}}{8\pi\sigma_x|x|} \right)^{1/2} e^{-\frac{\sqrt{3}|x|}{2\sigma_x}}$$

or by a simpler *Laplacian density*:

$$p_X(x) = \frac{1}{\sqrt{2}\sigma_x} e^{-\frac{\sqrt{3}|x|}{\sigma_x}}$$

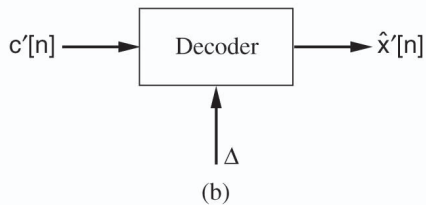
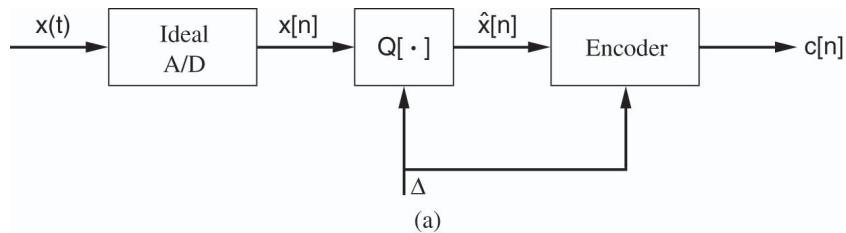
DENSITIES COMPARISON



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CODING AND DECODING



FUNDAMENTALS OF SCALAR CODING

- Let's quantize a single sample speech value, $x[n]$ into M *reconstruction* or *decision* levels:

$$\hat{x}[n] = \hat{x}_i = Q(x[n]), \quad x_{i-1} < x[n] \leq x_i$$

with $1 \leq i \leq M$ and x_k denotes the M decision levels with $0 \leq k \leq M$.

- Assign a *codeword* in each reconstruction level. Collection of codewords makes a *codebook*.
- Using B -bit binary codebook we can represent each 2^B different *quantization* (reconstruction) levels.
- *Bit rate*, I , is defined as: $I = Bf_s$

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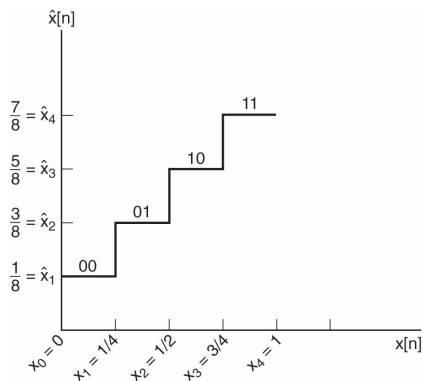
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UNIFORM QUANTIZATION

$$x_i - x_{i-1} = \Delta, \quad 1 \leq i \leq M$$
$$\hat{x}_i = \frac{x_i + x_{i-1}}{2}, \quad 1 \leq i \leq M$$

Δ is referred to as uniform quantization step size.

▷ Example of a 2-bit *uniform quantization*:



UNIFORM QUANTIZATION: DESIGNING DECISION REGIONS

- Signal range: $-4\sigma_x \leq x[n] \leq 4\sigma_x$
- Assuming B-bit binary codebook, we get 2^B quantization (reconstruction) levels
- Quantization step size, Δ :

$$\Delta = \frac{2x_{max}}{2^B}$$

- Δ and *quantization noise*.

CLASSES OF QUANTIZATION NOISE

There are two classes of quantization noise:

- Granular Distortion:

$$\hat{x}[n] = x[n] + e[n]$$

where $e[n]$ is the quantization noise, with:

$$-\frac{\Delta}{2} \leq e[n] \leq \frac{\Delta}{2}$$

- Overload Distortion: *clipped samples*

ASSUMPTIONS

- Quantization noise is an ergodic white-noise random process:

$$\begin{aligned}r_e[m] &= E(e[n]e[n+m]) \\ &= \sigma_e^2, \quad m = 0 \\ &= 0, \quad m \neq 0\end{aligned}$$

- Quantization noise and input signal are uncorrelated:

$$E(x[n]e[n+m]) = 0 \quad \forall m$$

- Quantization noise is uniform over the quantization interval

$$\begin{aligned}p_e(e) &= \frac{1}{\Delta}, \quad -\frac{\Delta}{2} \leq e \leq \frac{\Delta}{2} \\ &= 0, \quad \text{otherwise}\end{aligned}$$

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DEFINITION (DITHERING)

We can force $e[n]$ to be white and uncorrelated with $x[n]$ by adding noise to $x[n]$ before quantization!

SIGNAL-TO-NOISE RATIO

- To quantify the severity of the quantization noise, we define the *Signal-to-Noise Ratio* (SNR) as:

$$\begin{aligned} SNR &= \frac{\sigma_x^2}{\sigma_e^2} \\ &= \frac{E(x^2[n])}{E(e^2[n])} \\ &\approx \frac{\frac{1}{N} \sum_{n=0}^{N-1} x^2[n]}{\frac{1}{N} \sum_{n=0}^{N-1} e^2[n]} \end{aligned}$$

- For uniform pdf and quantizer range $2x_{max}$:

$$\begin{aligned} \sigma_e^2 &= \frac{\Delta^2}{12} \\ &= \frac{x_{max}^2}{3 \cdot 2^{2B}} \end{aligned}$$

- Or

$$SNR = \frac{3 \cdot 2^{2B}}{\left(\frac{x_{max}}{\sigma_x}\right)^2}$$

- and in dB:

$$SNR(dB) \approx 6B + 4.77 - 20 \log_{10} \left(\frac{x_{max}}{\sigma_x} \right)$$

- and since $x_{max} = 4\sigma_x$:

$$SNR(dB) \approx 6B - 7.2$$

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PULSE CODE MODULATION, PCM

- B bits of information per sample are transmitted as a codeword
- instantaneous coding
- not signal-specific
- 11 bits are required for “toll quality”
- what is the rate for $f_s = 10\text{kHz}$?
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OPTIMAL DECISION AND RECONSTRUCTION LEVEL

if $x[n] \mapsto p_x(x)$ we determine the optimal decision level, x_i and the reconstruction level, \hat{x} , by minimizing:

$$\begin{aligned} D &= E[(\hat{x} - x)^2] \\ &= \int_{-\infty}^{\infty} p_x(x)(\hat{x} - x)^2 dx \end{aligned}$$

and assuming M reconstruction levels $\hat{x} = Q[x]$:

$$D = \sum_{i=1}^M \int_{x_{i-1}}^{x_i} p_x(x)(\hat{x}_i - x)^2 dx$$

So:

$$\begin{aligned} \frac{\partial D}{\partial \hat{x}_k} &= 0, \quad 1 \leq k \leq M \\ \frac{\partial D}{\partial x_k} &= 0, \quad 1 \leq k \leq M - 1 \end{aligned}$$

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OPTIMAL DECISION AND RECONSTRUCTION LEVEL, *cont.*

- The minimization of D over decision level, x_k , gives:

$$x_k = \frac{\hat{x}_{k+1} + \hat{x}_k}{2}, \quad 1 \leq k \leq M - 1$$

- The minimization of D over reconstruction level, \hat{x}_k , gives:

$$\begin{aligned}\hat{x}_k &= \int_{x_{k-1}}^{x_k} \left[\frac{p_x(x)}{\int_{x_{k-1}}^{x_k} p_x(s) ds} \right] x dx \\ &= \int_{x_{k-1}}^{x_k} \tilde{p}_x(x) x dx\end{aligned}$$

OPTIMAL DECISION AND RECONSTRUCTION LEVEL, *cont.*

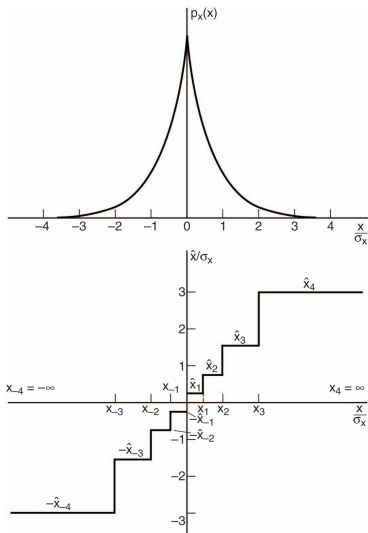
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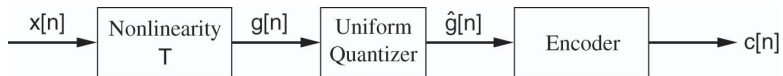
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EXAMPLE WITH LAPLACIAN PDF



PRINCIPLE OF COMPANDING



(a)



(b)

COMPANDING EXAMPLES

Companding examples:

- Transformation to a uniform density:

$$g[n] = T(x[n]) = \int_{-\infty}^{x[n]} p_x(s) ds - \frac{1}{2}, \quad \frac{-1}{2} \leq g[n] \leq \frac{1}{2}$$
$$= 0 \quad \text{elsewhere}$$

- μ -law:

$$T(x[n]) = x_{max} \frac{\log(1 + \mu \frac{|x[n]|}{x_{max}})}{\log(1 + \mu)} \text{sign}(x[n])$$

COMPANDING EXAMPLES

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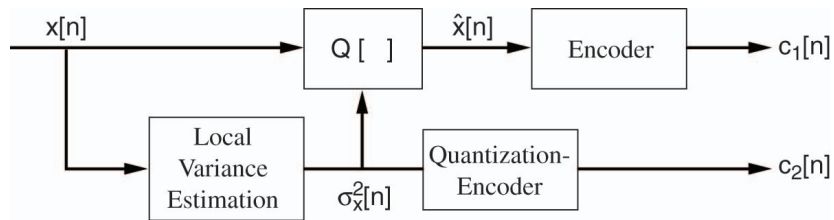
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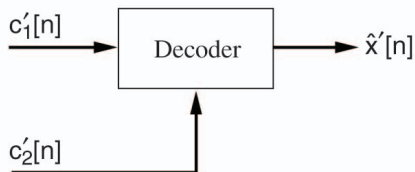
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ADAPTIVE QUANTIZATION

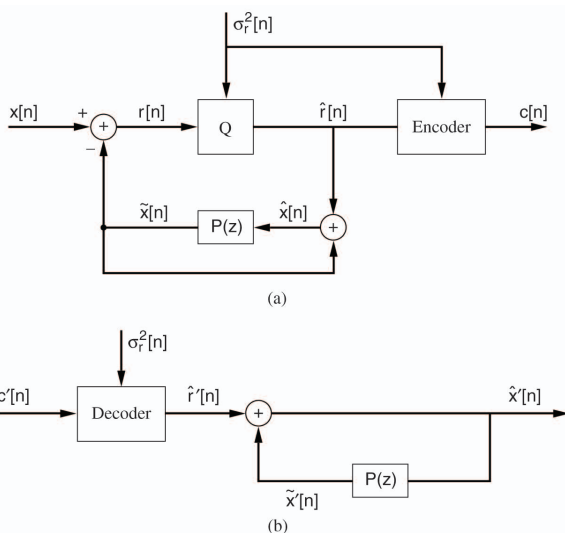


(a)



(b)

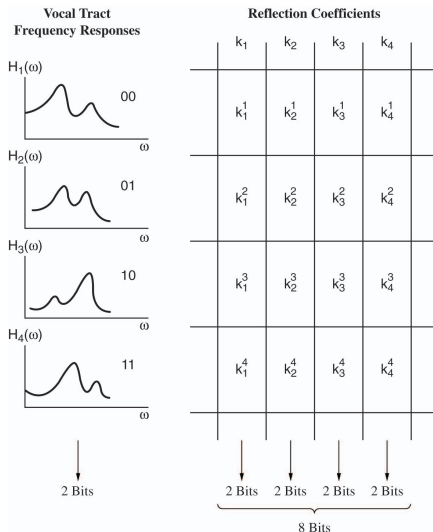
DIFFERENTIAL AND RESIDUAL QUANTIZATION



OUTLINE

- 1 INTRODUCTION
- 2 STATISTICAL MODELS
- 3 SCALAR QUANTIZATION
 - Max Quantizer
 - Companding
 - Adaptive quantization
 - Differential and Residual quantization
- 4 VECTOR QUANTIZATION
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 - The LBG algorithm
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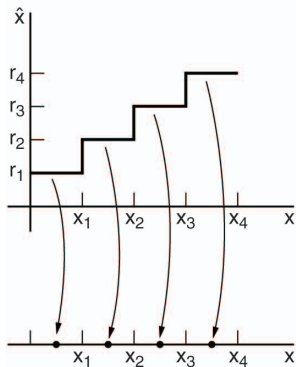
MOTIVATION FOR VQ



COMPARING SCALAR AND VECTOR QUANTIZATION

Max quantizer (1-D)

$$\hat{x} = Q[x]$$

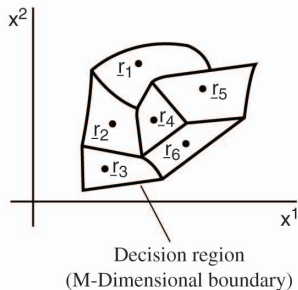


• = Centroid over the decision interval

$$D = E [(\hat{x} - x)^2]$$

Vector quantizer (2-D)

$$\hat{\underline{x}} = VQ[\underline{x}]$$



• = Centroid over the decision region

$$D = E [(\hat{\underline{x}} - \underline{x})^2(\hat{\underline{x}} - \underline{x})]$$

DISTORTION IN VQ

Here we have a multidimensional pdf $p_{\mathbf{x}}(\mathbf{x})$:

$$\begin{aligned} D &= E[(\hat{\mathbf{x}} - \mathbf{x})^T (\hat{\mathbf{x}} - \mathbf{x})] \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} (\hat{\mathbf{x}} - \mathbf{x})^T (\hat{\mathbf{x}} - \mathbf{x}) p_{\mathbf{x}}(\mathbf{x}) d\mathbf{x} \\ &= \sum_{i=1}^M \int \int_{\mathbf{x} \in \mathcal{C}_i} \cdots \int (\mathbf{r}_i - \mathbf{x})^T (\mathbf{r}_i - \mathbf{x}) p_{\mathbf{x}}(\mathbf{x}) d\mathbf{x} \end{aligned}$$

Two constraints:

- A vector \mathbf{x} must be quantized to a reconstruction level \mathbf{r}_i that gives the smallest distortion:

$$\mathcal{C}_i = \{\mathbf{x} : \|\mathbf{x} - \mathbf{r}_i\|^2 \leq \|\mathbf{x} - \mathbf{r}_l\|^2, \forall l = 1, 2, \dots, M\}$$

- Each reconstruction level \mathbf{r}_i must be the centroid of the corresponding decision region, i.e., of the cell \mathcal{C}_i :

$$\mathbf{r}_i = \frac{\sum_{\mathbf{x}_m \in \mathcal{C}_i} \mathbf{x}_m}{\sum_{\mathbf{x}_m \in \mathcal{C}_i} 1} \quad i = 1, 2, \dots, M$$

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THE K-MEANS ALGORITHM

- S1:

$$D = \frac{1}{N} \sum_{k=0}^{N-1} (\hat{\mathbf{x}}_k - \mathbf{x}_k)^T (\hat{\mathbf{x}}_k - \mathbf{x}_k)$$

- S2: Pick an initial guess at the reconstruction levels $\{\mathbf{r}_i\}$
- S3: For each \mathbf{x}_k elect an \mathbf{r}_i closest to \mathbf{x}_k . Form clusters (*clustering step*)
- S4: Find the mean of \mathbf{x}_k in each cluster which gives a new \mathbf{r}_i . Compute D .
- S5: Stop when the change in D over two consecutive iterations is insignificant.

THE LBG ALGORITHM

- Set the *desired* number of cells: $M = 2^B$
- Set an initial codebook $\mathcal{C}^{(0)}$ with *one* codevector which is set as the average of the entire training sequence, \mathbf{x}_k , $k = 1, 2, \dots, N$.
- Split the codevector into two and get an *initial* new codebook $\mathcal{C}^{(1)}$.
- Perform a k-means algorithm to optimize the codebook and get the *final* $\mathcal{C}^{(1)}$
- Split the final codevectors into four and repeat the above process until the desired number of cells is reached.

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BASIC CODING SCHEME IN LPC

- Vocal tract system function:

$$H(z) = \frac{A}{1 - P(z)}$$

where

$$P(z) = \sum_{k=1}^p a_k z^{-1}$$

- Input is binary: impulse/noise excitation.
- If frame rate is 100 frames/s and we use 13 parameters ($p = 10$, 1 for Gain, 1 for pitch, 1 for voicing decision) we need 1300 parameters/s, instead of 8000 samples/s for $f_s = 8000\text{Hz}$.

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SCALAR QUANTIZATION WITHIN LPC

For 7200 bps:

- Voiced/unvoiced decision: 1 bit
- Pitch (if voiced): 6 bits (uniform)
- Gain: 5 bits (nonuniform)
- Poles d_i : 10 bits (nonuniform) [5 bits for frequency and 5 bits for bandwidth] \times 6 poles = 60 bits

So: $(1 + 6 + 5 + 60) \times 100 \text{ frames/s} = 7200 \text{ bps}$

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- Companding in the form of a logarithmic operator on pitch and gain
- Instead of poles use the reflection (or the PARCOR) coefficients k_i , (nonuniform)
- Companding of k_i :

$$\begin{aligned}g_i &= T[k_i] \\ &= \log\left(\frac{1-k_i}{1+k_i}\right)\end{aligned}$$

- Coefficients g_i can be coded at 5-6 bits each! (which results in 4800 bps for an order 6 predictor, and 100 frames/s)
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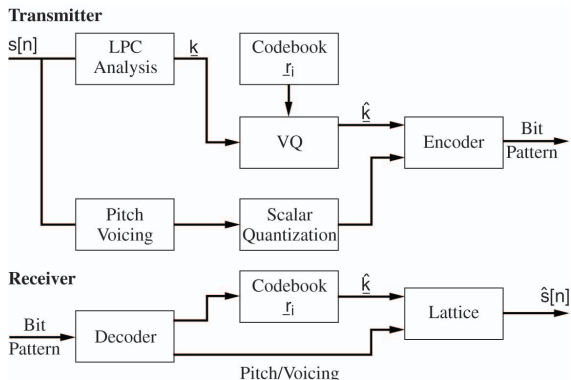
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VQ IN LPC CODING

- ▷ A 10-bit codebook (1024 codewords), 800 bps VQ provides a comparable quality to a 2400 bps scalar quantizer.
- ▷ A 22-bit codebook (4200000 codewords), 2400 bps VQ provides a higher output speech quality.



UNIQUE COMPONENTS OF MELP

- Mixed pulse and noise excitation
- Periodic or aperiodic pulses
- Adaptive spectral enhancements
- Pulse dispersion filter

LINE SPECTRAL FREQUENCIES (LSFs) IN MELP

LSFs for a p th order all-pole model are defined as follows:

- 1 Form two polynomials:

$$\begin{aligned}P(z) &= A(z) + z^{-(p+1)}A(z^{-1}) \\Q(z) &= A(z) - z^{-(p+1)}A(z^{-1})\end{aligned}$$

- 2 Find the roots of $P(z)$ and $Q(z)$, ω_i which are on the unit circle.
- 3 Exclude trivial roots at $\omega_i = 0$ and $\omega_i = \pi$.

For a 2400 bps:

- 34 bits allocated to scalar quantization of the LSFs
- 8 bits for gain
- 7 bits for pitch and overall voicing
- 5 bits for multi-band voicing
- 1 bit for the jittery state

which is 54 bits. With a frame rate of 22.5 ms, we get an 2400 bps coder.

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Most, if not all, figures in this lecture are coming from the book:

T. F. Quatieri: Discrete-Time Speech Signal Processing,
principles and practice
2002, Prentice Hall

and have been used after permission from Prentice Hall

