#### CS425 Computer Systems Architecture

#### Fall 2017

#### **Thread Level Parallelism (TLP)**

CS425 - Vassilis Papaefstathiou

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### **Multiple Issue**

 $CPI = CPI_{IDEAL} + Stalls_{STRUC} + Stalls_{RAW} + Stalls_{WAR} + Stalls_{WAW} + Stalls_{CONTROL}$ 

- Have to maintain:
  - Data Flow
  - Exception Behavior

Dynamic instruction scheduling (HW)	Static instruction scheduling (SW/compiler)
Scoreboard (reduce RAW stalls)	Loop Unrolling
<ul> <li>Register Renaming (reduce WAR &amp; WAW stalls)</li> <li>•Tomasulo</li> <li>• Reorder buffer</li> </ul>	SW pipelining
Branch Prediction (reduce control stalls)	Trace Scheduling
Multiple Issue (CPI < 1) Multithreading (CPI < 1)	

### **Common Way of Designing Architectures**

- Networking, single/multi-core processor, virtually any design:
  - Broadcasting: Use Common Data Bus or Point to point
  - Asynchronous communication between "processing stages" with different throughputs (a processing stage can be a whole system, for example router, switch, processor, or a simple block, for example IF, ID stages). Use Elastic Buffer & Flow Control. For example instruction buffer, reservation stations and reorder buffer
  - Faster clock: Pipelining. Split a stage in multiple stages. For example split Issue stage (super-pipelining)
  - Higher Throughput: Parallel processing. For example superscalar.
  - Lower Latency: Forwarding/Bypassing
- A processor is a sophisticated design that follows the "unwritten" design rules every architect should follow.

### Multithreading

- Difficult to continue to extract ILP from a single thread
- Many workloads can make use of thread-level parallelism (TLP)
  - TLP from multiprogramming (run independent sequential jobs)
  - TLP from multithreaded applications (run one job faster using parallel threads)
- Multithreading uses TLP to improve utilization of a single processor

#### **Pipeline Hazards**

.t2 .t3 .t4 .t5 .t6 .t7 .t8 .t9 .t10.t11.t12.t13.t14. <u>t0</u>t1 F X D LW r1, 0(r2) IVI MW X LW r5, 12(r1) F D D D D F **M**|W ADDI r5, r5, #12 F D X F F D D D SW 12(r1), r5 F F F D F D D D

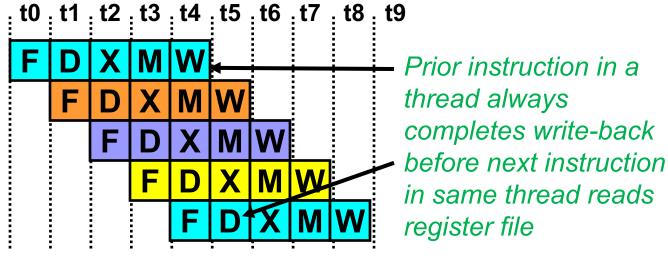
- Each instruction may depend on the next
- What can be done to cope with this?

### **Solution with Multithreading**

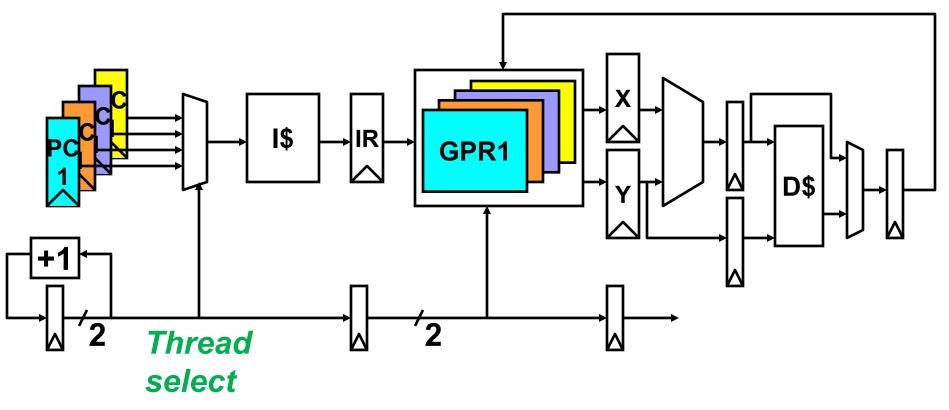
- How can we guarantee no dependencies between instructions in a pipeline?
  - One way is to interleave execution of instructions from different program threads on same pipeline

#### Interleave 4 threads, T1-T4, on non-bypassed 5-stage pipe

T1: LW r1, 0(r2) T2: ADD r7, r1, r4 T3: XORI r5, r4, #12 T4: SW 0(r7), r5 T1: LW r5, 12(r1)



#### **Multithreaded DLX**



- Have to carry thread select down to the pipeline to ensure that the correct state bits are read/written at each pipe stage
- Appears to software (including OS) as multiple, albeit slower, CPUs

### **Multithreading Cost**

• Each thread requires its own user state. Many CPU resources are split or shared!

– PC

- GPRs & Physical/HW registers
- Prefetch & Instruction buffers
- Reorder buffer
- Load/Store buffer
- Issue buffers
- Also, needs its own system state
  - virtual memory page table base register
  - exception handling registers
- Other costs?
- Take care of performance when executing in Single Thread (ST) mode!

### **Thread Scheduling Policies**

- Fixed interleaving (CDC 6600 PPUs, 1964)
  - -each of N threads executes one instruction every N cycles
  - if thread not ready to go in its slot, insert pipeline bubble
- Software-controlled interleave (TLASC PPUs, 1971)
  - -OS allocates S pipeline slots amongst N threads
  - hardware performs fixed interleave over S slots, executing whichever thread is in that slot

- Hardware-controlled thread scheduling (HEP, 1982) (Power 5)
  - -hardware keeps track of which threads are ready to go
  - picks next thread to execute based on hardware priority scheme

#### Fine-Grain Multithreading

Fine-grain multithreading switches processor context every thread cycle

#### Context belongs to same address space

Fine-grain multithreading	Cycle-1	Cycle-2	Cycle-3	Cycle-4	Cycle-5	Cycle-6	Cycle-7	Cycle-8
Processor context								
	Thread-1	Thread-2	Thread-1	Thread-2	Thread-1	Thread-2	Thread-1	Thread-2
	Cycle-1	Cycle-2	Cycle-1	Cycle-2	Cycle-1	Cycle-2	Cycle-1	Cycle-2

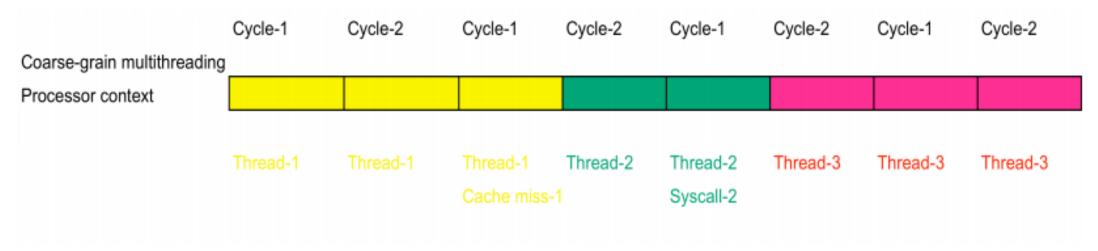
#### Fine-Grain Multithreading

#### Switch every clock cycle

- Need fast HW switch between contexts
  - Multiple PCs and register files
  - Alternatively, thread ID attached to each GP register
- Implemented with round-robin scheduling, skipping stalled threads
- Hides both short and long stalls
- Delays all threads, even if they have no stalls

#### Coarse-Grain Multithreading

- Coarse-grain multithreading switches processor context upon long-latency event
- Context may belong to different address space



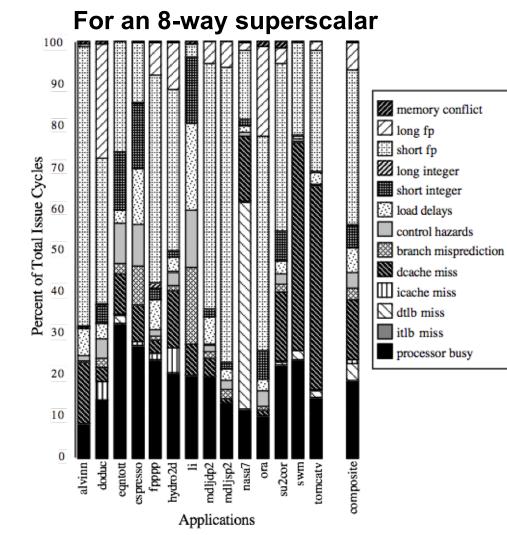
#### Coarse-Grain Multithreading

#### Switch upon long upon long-latency events

- Can afford slower context switch than fine-grain multithreading
- Threads are not slowed down
  - Other thread runs when current thread stalls
- Pipeline startup cost upon thread switching
  - Processor issues instructions from one thread (address space)

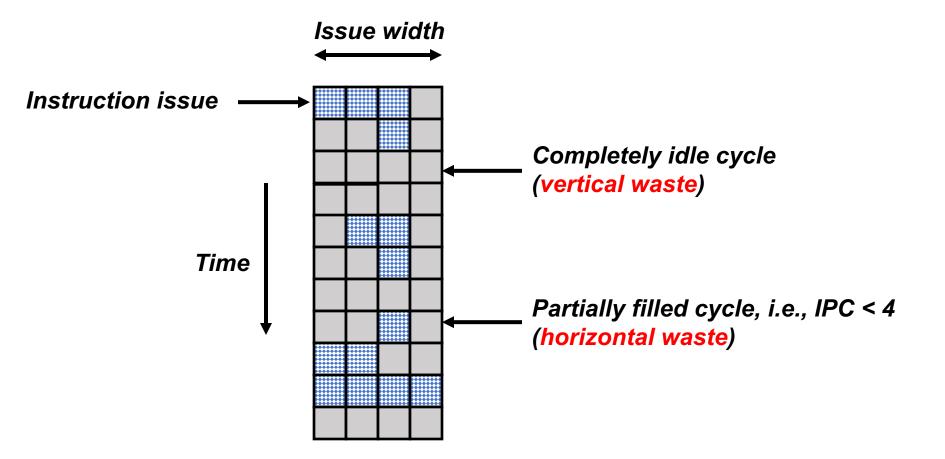
- Simultaneous Multithreading (SMT)
- Techniques presented so far have all been "vertical" multithreading where each pipeline stage works on one thread at a time
- SMT uses fine-grain control already present inside an OoO superscalar to allow instructions from multiple threads to enter execution on same clock cycle. Gives better utilization of machine resources.

# For most apps, most execution units are idle in an OoO superscalar

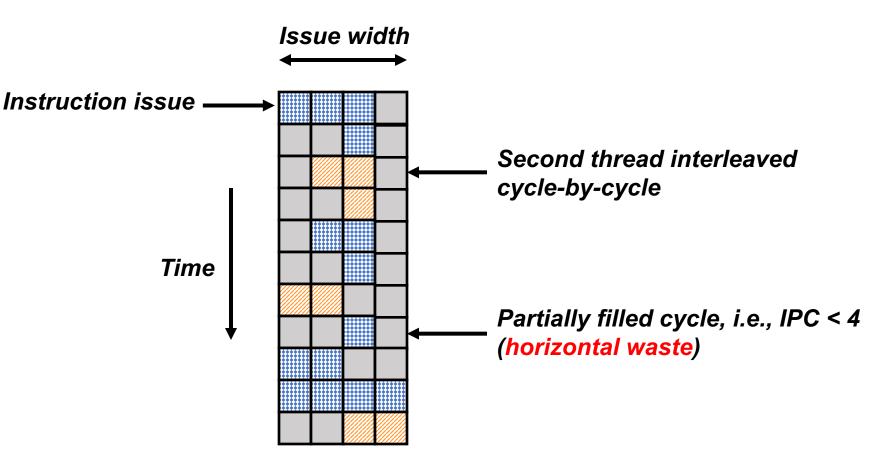


From: Tullsen, Eggers, and Levy, "Simultaneous Multithreading: Maximizing On-chip Parallelism, ISCA 1995.

#### **Superscalar Machine Efficiency**



### **Vertical Multithreading**

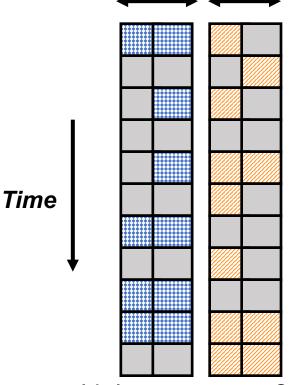


• What is the effect of cycle-by-cycle interleaving?

- removes vertical waste, but leaves some horizontal waste

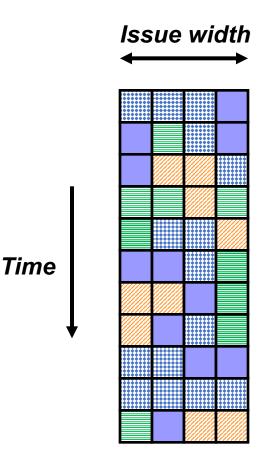
## **Chip Multiprocessing (CMP)**

Issue width



- What is the effect of splitting into multiple processors?
  - reduces horizontal waste,
  - leaves some vertical waste, and
  - puts upper limit on peak throughput of each thread  $\rightarrow$  single thread execution is slower

#### Ideal Superscalar Multithreading: SMT [Tullsen, Eggers, Levy, UW, 1995]

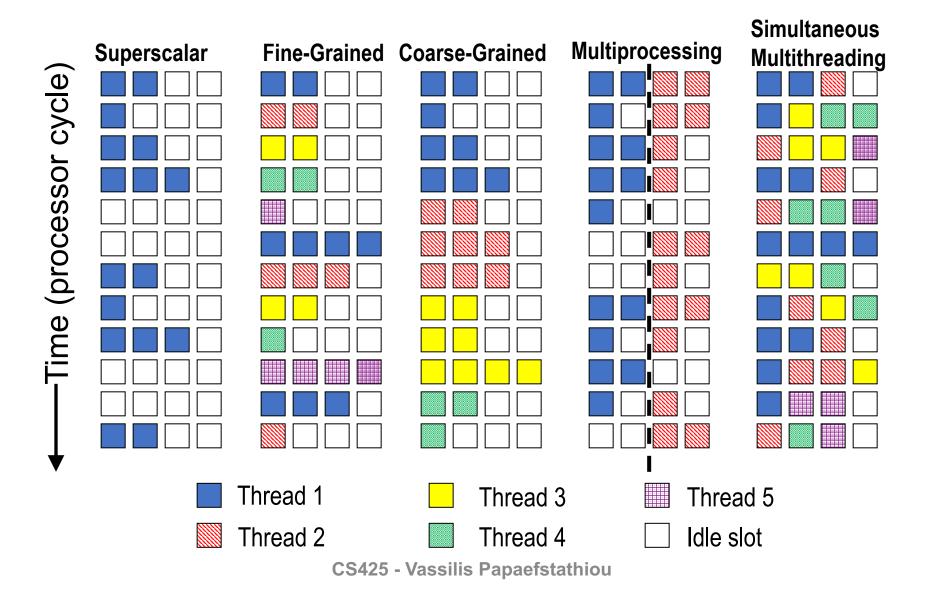


Interleave multiple threads to multiple issue slots with no restrictions

#### **O-o-O Simultaneous Multithreading** [Tullsen, Eggers, Emer, Levy, Stamm, Lo, DEC/UW, 1996]

- Add multiple contexts and fetch engines and allow instructions fetched from different threads to issue simultaneously
- Utilize wide out-of-order superscalar processor issue queue to find instructions to issue from multiple threads
- OOO instruction window already has most of the circuitry required to schedule from multiple threads
- Any single thread can utilize whole machine
- Shared HW mechanisms
  - Large set of virtual registers can hold register sets of independent threads
  - Renaming provides unique register identifiers to different threads
  - Out-of-order completion of instructions from different threads allowed
  - No cross-thread RAW, WAW, WAR hazards
  - Separate re-order buffer per thread

#### **Summary: Multithreaded Categories**

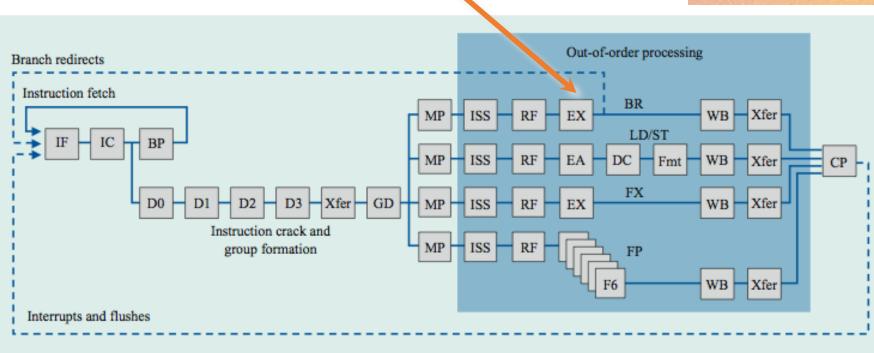


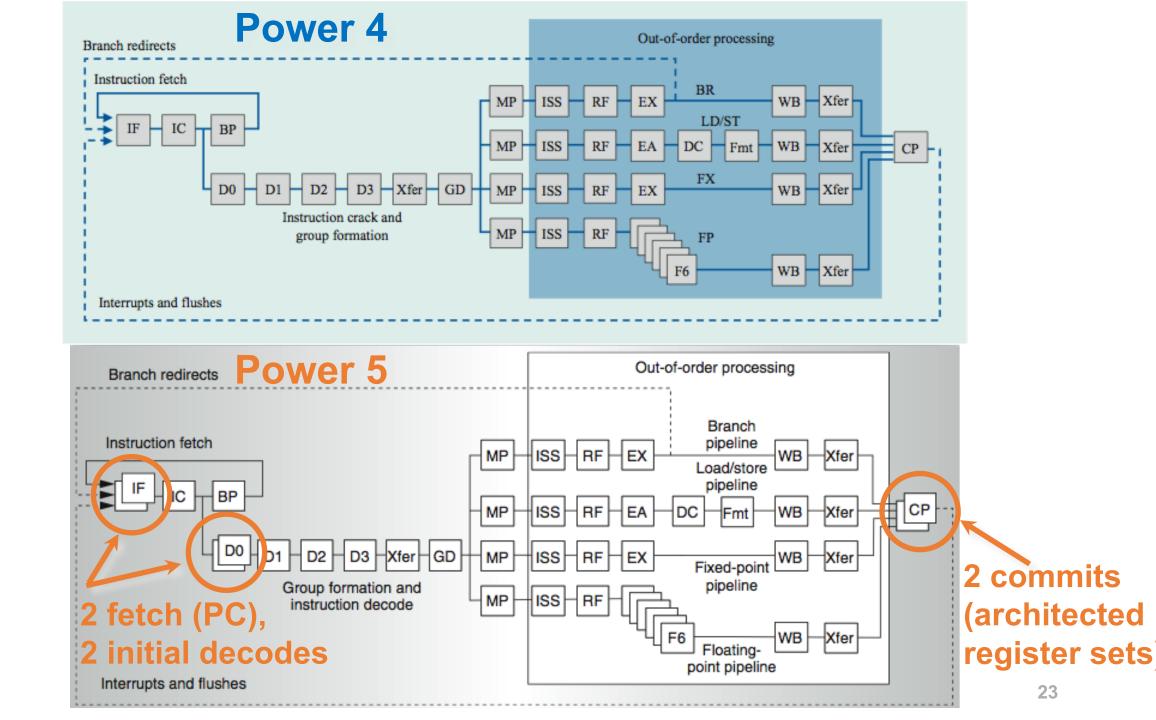
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#### **IBM Power 4**

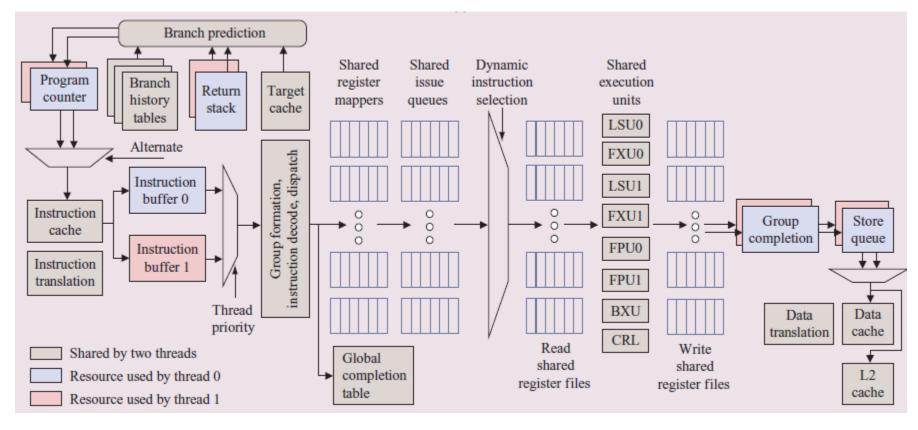
Single-threaded predecessor to Power 5. 8 execution units in out-of-order engine, each may issue an instruction each cycle.







#### Power 5 data flow ...



• Why only 2 threads? With 4, one of the shared resources (physical registers, cache, memory bandwidth) would be prone to bottleneck

#### **Rename Registers and issue queue sizes**

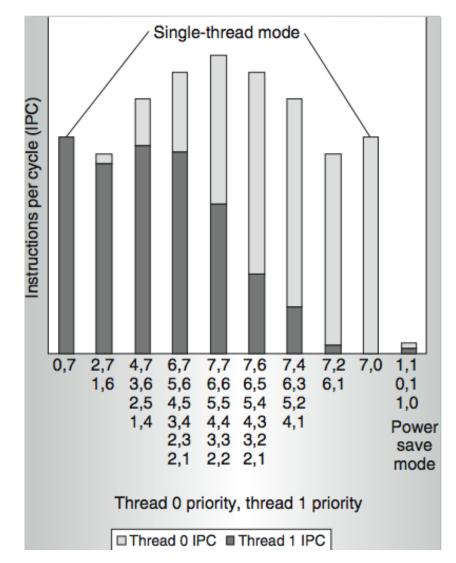
Resource type	Logical size (per thread)	Physical size		
		POWER4	POWER5	
GPRs	32 (+4)	80	120	
FPRs	32	72	120	
$\operatorname{CRs}^{\dagger}$	8 (+1) 4-bit fields	32	40	
Link/count registers	2	16	16	
$FPSCR^{\dagger}$	1	20	20	
$\mathbf{XER}^{\dagger}$	Four fields	24	32	
Fixed-point and load/store issue queue	Shared by both threads	36	36	
Floating-point issue queue	Shared by both threads	20	24	
Branch execution issue queue	Shared by both threads 12		12	
CR logical issue queue	Shared by both threads	10	10	

### **Changes in Power 5 to support SMT**

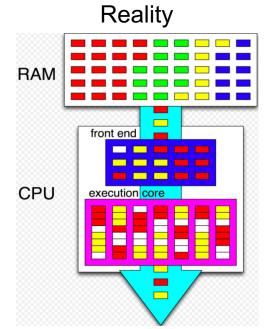
- Two separate program counters are used, one for each thread
- Added per thread load and store queues. Added virtual entries.
- The size of the BIQ (Branch Information Queue) remains at 16 entries but split in two, with eight entries per thread.
- Added separate instruction prefetch and buffering per thread.
- Each logical register number has a thread bit appended and mapped as usual. Increased the number of physical registers from 152 to 240
- Increased the size of FP issue queue.
- Shared global completion table (GCT). Two linked lists to implement in order commit from the two threads.
- The Power5 core is about 24% larger than the Power4 core because of the addition of SMT support

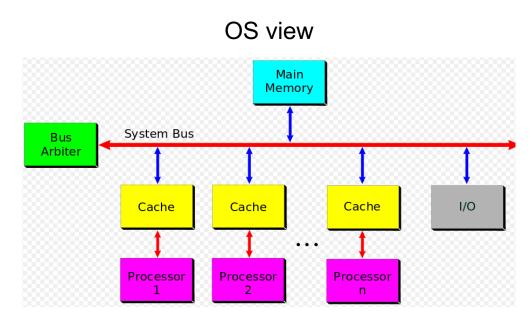
### **Power 5 thread performance**

- Priority is set by SW and enforced by HW.
- Relative priority of each thread controllable in hardware.
- For balanced operation, both threads run slower than if they "owned" the machine.



### Intel Hyper-Threading Technology





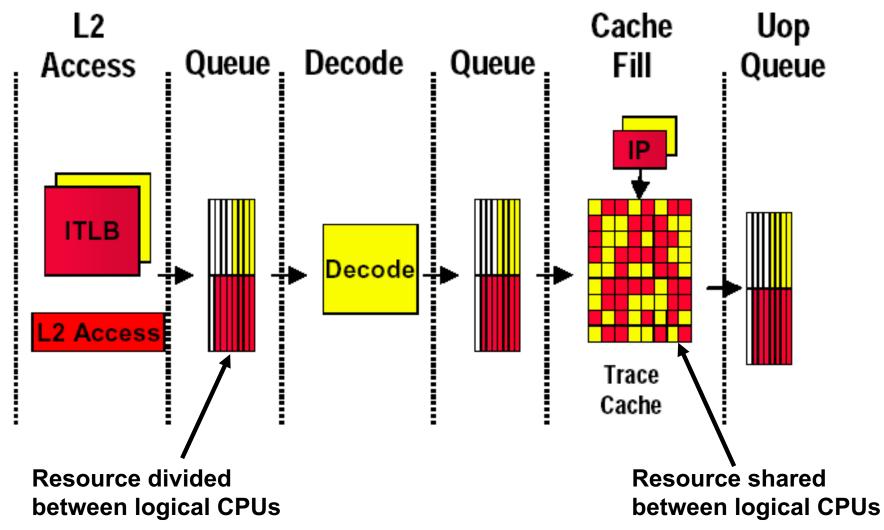
- Hyper-Threading Technology is SMT introduced by Intel. HTT has two logical processors, with its own processor architectural state
- HTT duplicates the architectural state but not the main execution resources
- Transparent to OS: minimum requirement is symmetric multiprocessing (SMP) support
- SMP involves two or more identical processors connect to a single, shared main memory, all I/O devices, controlled by single OS

### Pentium-4 Hyperthreading (2002)

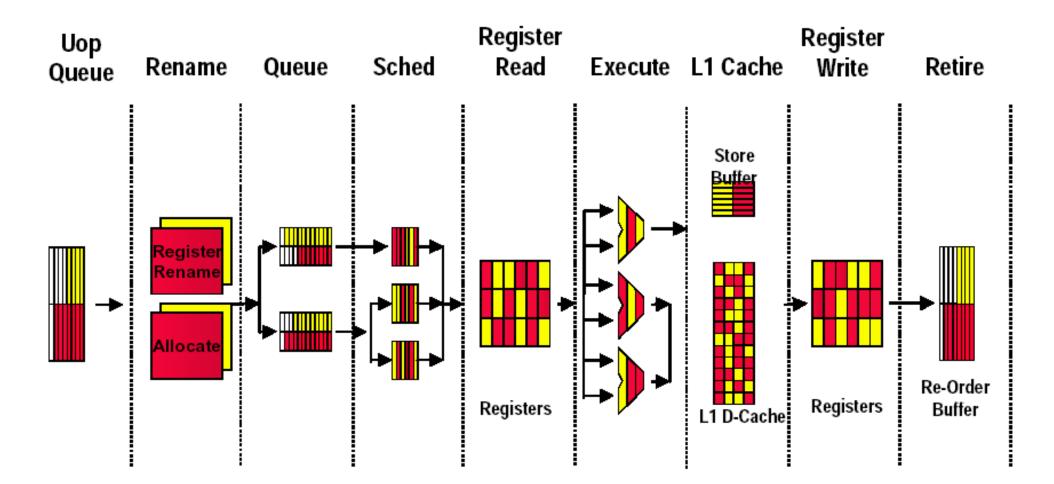
- First commercial SMT design (2-way SMT)
  - Hyperthreading == SMT
- Logical processors share nearly all resources of the physical processor
  - Caches, execution units, branch predictors
- Die area overhead of hyperthreading ~ 5%
- When one logical processor is stalled, the other can progress

   No logical processor can use all entries in queues when two threads are active
- Processor running only one active software thread runs at approximately same speed with or without hyperthreading

### **Pentium-4 Hyperthreading: Front End**



### **Pentium-4 Hyperthreading: Execution Pipe**



#### [Intel Technology Journal, Q1 2002]

### **Initial Performance of SMT**

#### Multi-program workloads

- Pentium 4 Extreme SMT achieves 1.01 speedup for SPECint\_rate benchmark and 1.07 for SPECfp\_rate
  - Pentium 4 is dual-threaded SMT
  - SPECRate requires that each SPEC benchmark be run against a vendor-selected number of copies of the same benchmark
- Running on Pentium 4 each of 26 SPEC benchmarks paired with every other (26<sup>2</sup> runs) speed-ups from 0.90 to 1.58; average is 1.20
- Power 5, 8 processor server 1.23 faster for SPECint\_rate with SMT, 1.16 faster for SPECfp\_rate
- Power 5 running 2 copies of each app speedup between 0.89 and 1.41 Most gained some FP apps had cache conflicts and least gains

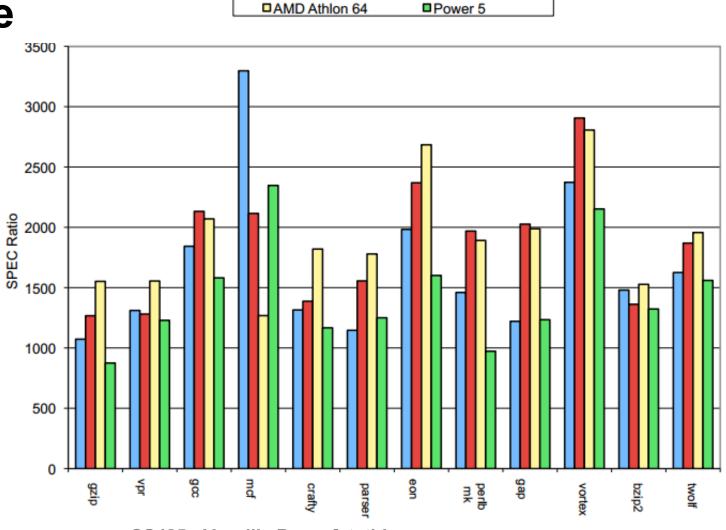
### **Comparison of multiple-issue processors**

Processor	Microarchitecture	Fetch/ issue/ execute	Func. units	Clock rate (GHz)	Transistors and die size	Power
Intel Pentium 4 Extreme	Speculative dynamically scheduled; deeply pipelined; SMT	3/3/4	7 int. 1 FP	3.8	125M 122 mm <sup>2</sup>	115 W
AMD Athlon 64 FX-57	Speculative dynamically scheduled	3/3/4	6 int. 3 FP	2.8	114M 115 mm <sup>2</sup>	104 W
IBM Power5 1 processor	Speculative dynamically scheduled; SMT; two CPU cores/chip	8/5/8	6 int. 2 FP	1.9	200M 300 mm <sup>2</sup> (estimated)	80 W (estimated)
Intel Itanium 2	EPIC style; primarily statically scheduled	6/5/11	9 int. 2 FP	1.6	592M 423 mm <sup>2</sup>	130 W

#### **ILP Comparison of multiple-issue processors**

Itanium 2

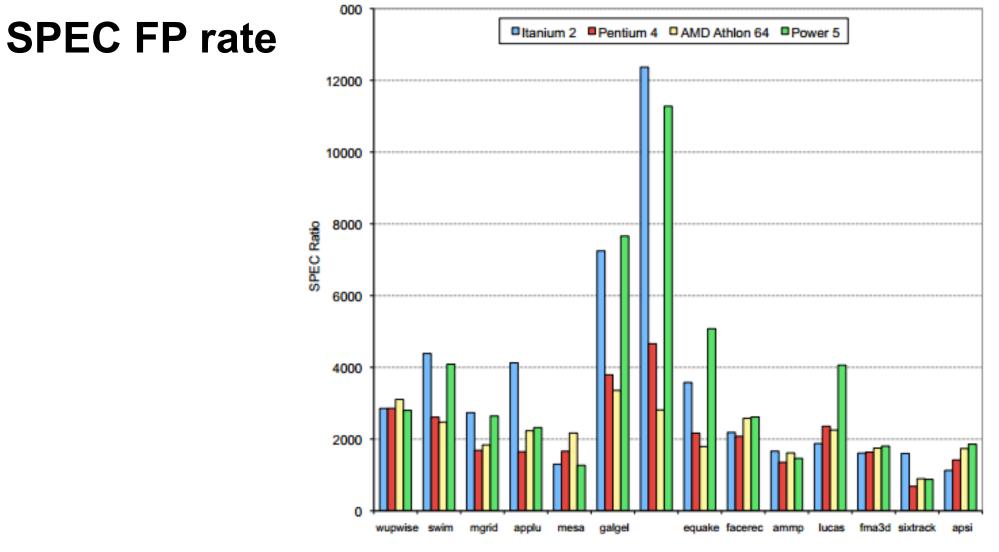
**SPEC INT rate** 



Pentium 4

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#### **ILP Comparison of multiple-issue processors**



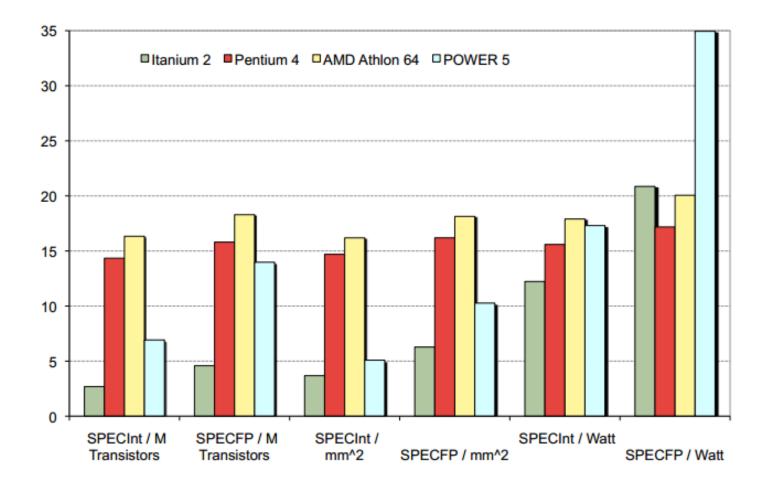
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### Measuring processor efficiency

#### Area- and power-efficiency

- Processor performance gain comes at an area/power budget cost
  - Weigh performance again against power and area increase
- Area-efficiency
  - Performance / transistor (e.g. SPECrate/million transistors)
- Power-efficiency
  - Performance / watt (e.g. SPECrate/watt)

### ILP Comparison of multiple-issue processors Power and area efficiency



### **Best ILP approach?**

#### **Results with commercial processors**

- AMD Athlon most performance-efficient in INT programs
- Power5 most performance-efficient in FP programs
- Power5 most power-efficient overall
- Itanium VLIW least power-efficient and area-efficient overall