HY425 Lecture 14: Improving Cache Performance II

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November 30, 2011

Parallelism

Overlapping memory latency with instructions

- Allow processor to work while memory serves requests
- Overlap memory latency with other instructions
- Essential in out-of-order processors

Hide memory latency with prefetching

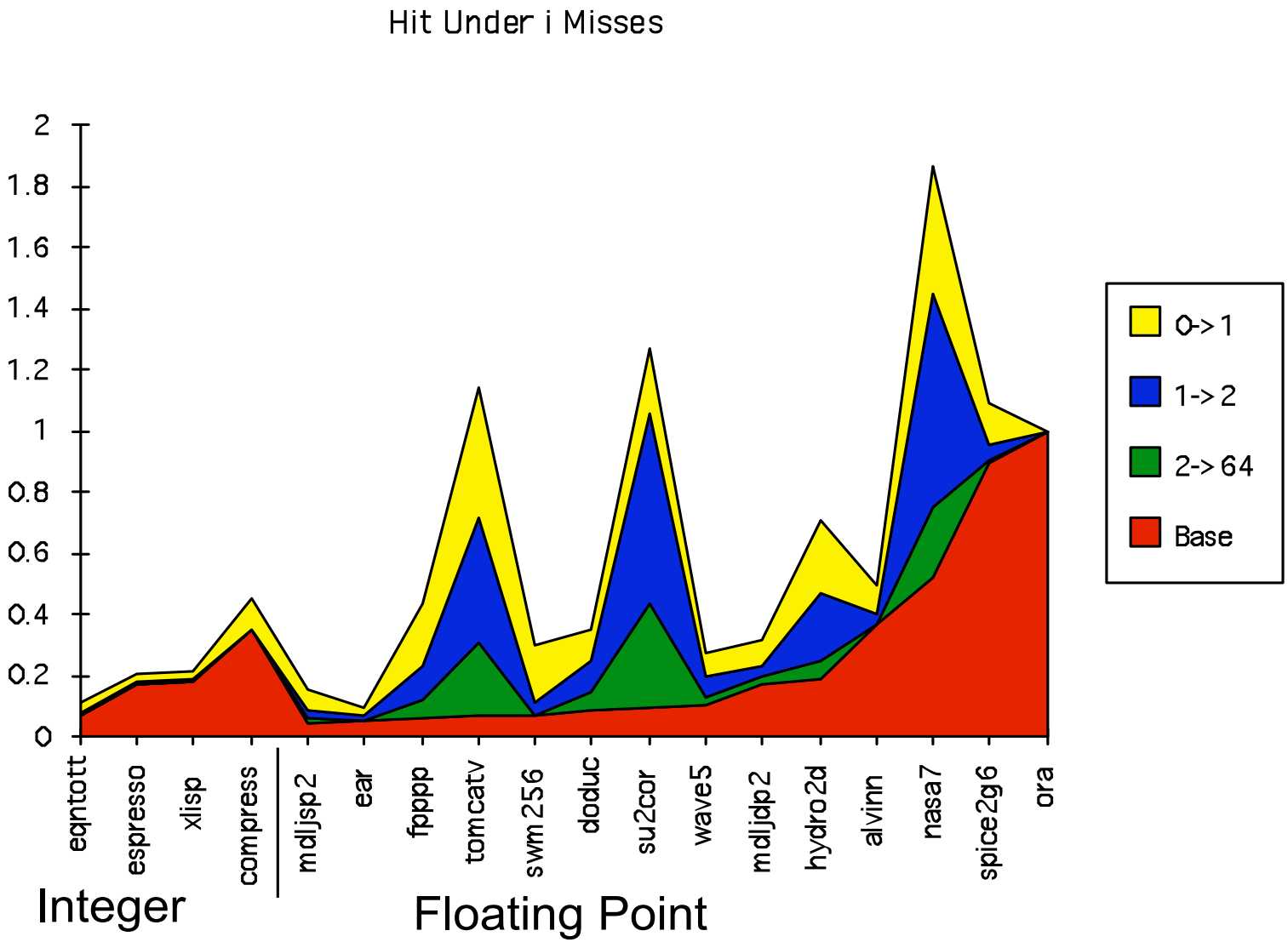
- Allow processor to prefetch extra data
- If data useful and fetched in time, reduces memory latency

Non-blocking caches

Hit under miss

- Processor continues execution while miss pending
- Cache serves hits while miss pending
- Need check for dependence violations
  - Logic for memory RAW, WAW, WAR, hazards
  - Dynamic issue processor
- Can overlap multiple misses
  - Requires suitable multi-bank, pipelined memory system
- Hard to measure miss penalty due to overlap of hits and misses

Hit under miss performance impact



Prefetching

Reduce memory latency

- Processor requests data in advance
  - Processor speculates that requested data will be accessed in the future
- Need a guess for what data will be needed in the future
- Guess easy in linear memory access pattern
  - Fixed stride between data accesses
  - Strided prefetching
- Need prefetch triggers, e.g. two consecutive misses

Prefetching

Performance implications

- Prefetched data may displace other useful data from cache
- Prefetched data may come too early and be evicted before used
- Prefetched data may come too late and not be there when needed
- Prefetched data may be useless, i.e. not accessed at all
- Prefetched data wastes memory bandwidth, if useless

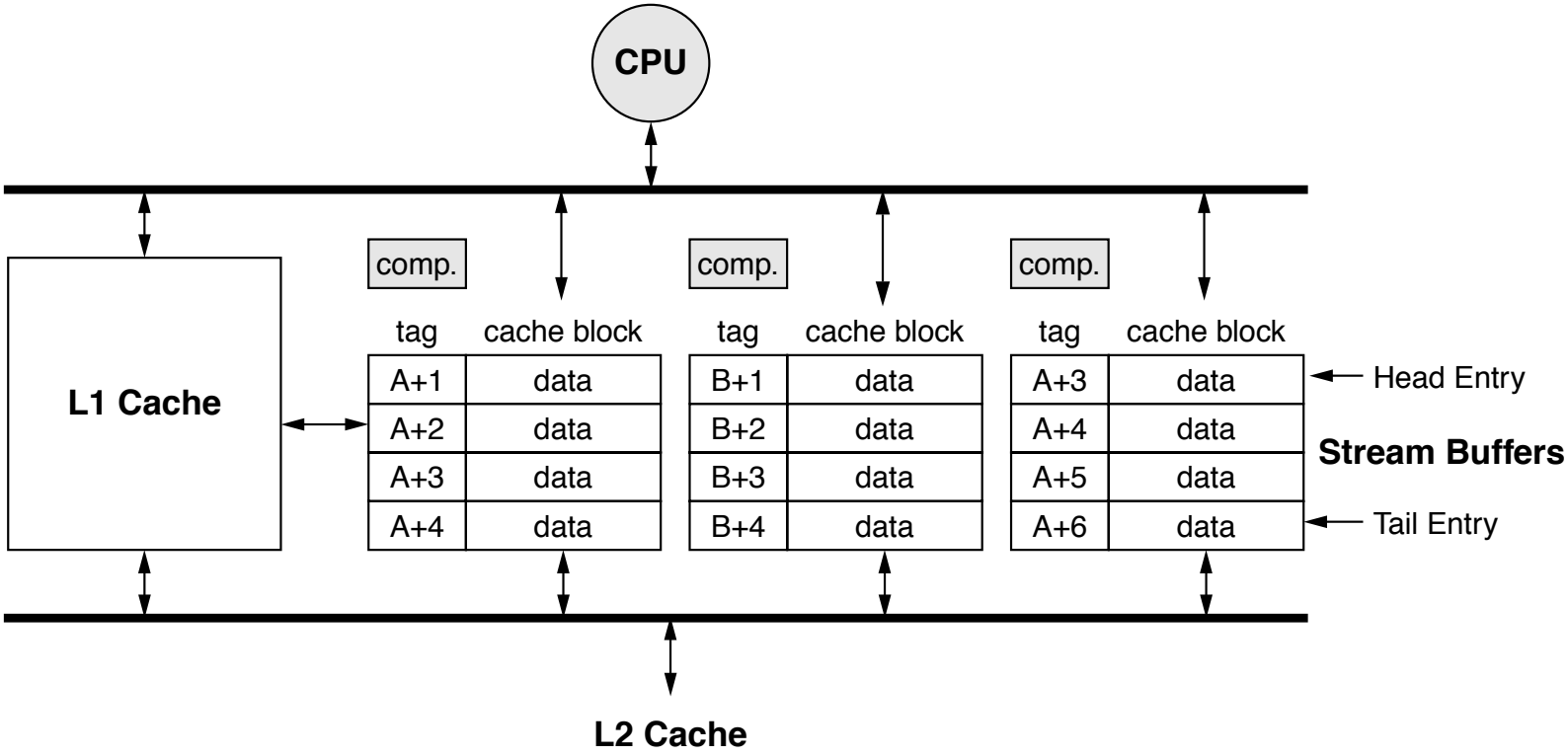
Online Prefetching Heuristics

- Prefetching helps codes with non-perfect spatial locality
- Can be initiated at any level of the memory hierarchy
- Prefetched data can be stored at any level of the memory hierarchy
- Branch prediction is a form of prefetching
  - Prefetching instructions ahead of their execution
- Simple lookahead prefetching
  - Prefetch block i+1 (or i+2, or i+3,...) upon demand fetching block i
  - Prefetch i+1 called next-line prefetching

Lookahead prefetching

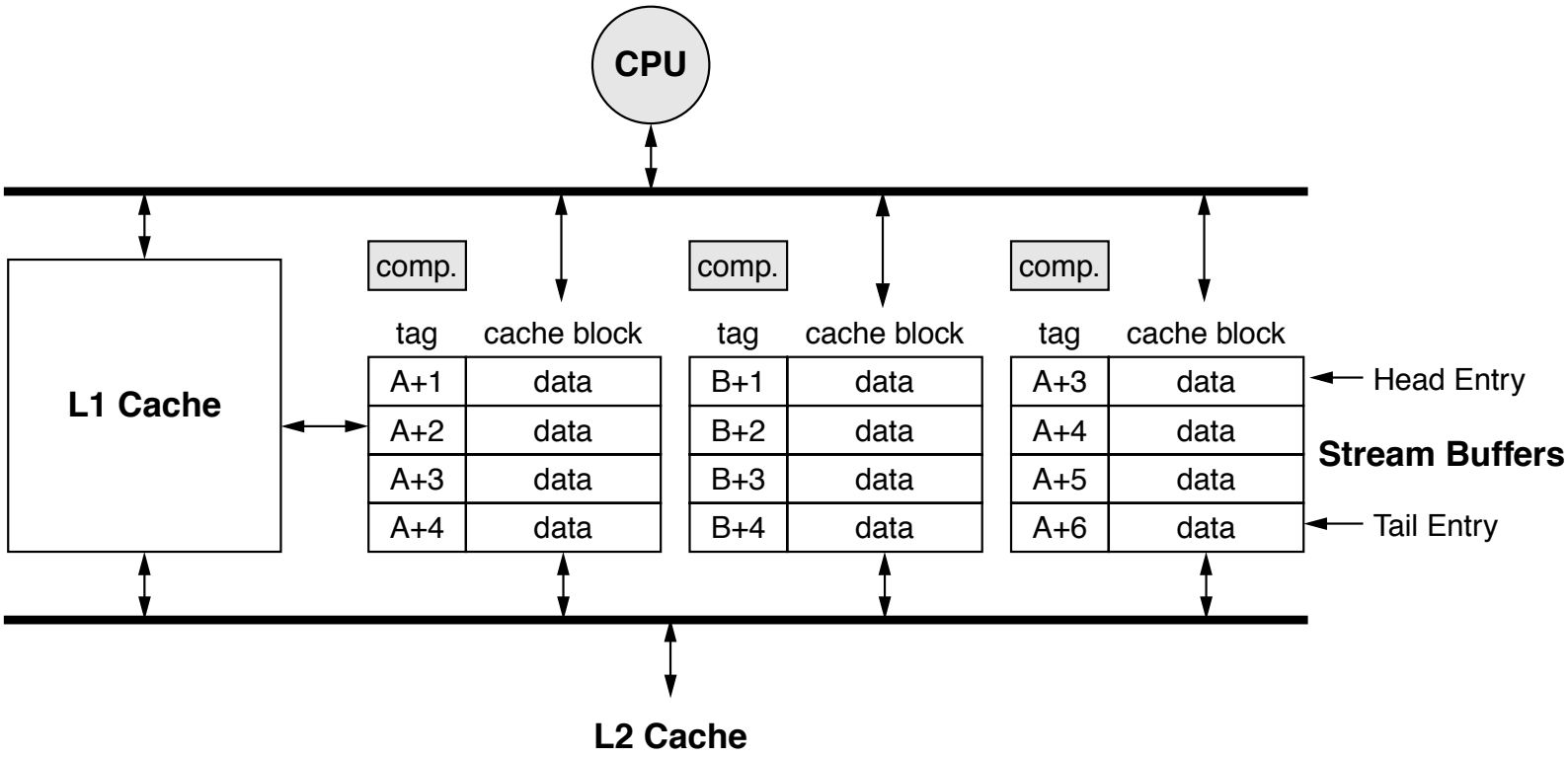
- Three ways to prefetch:
  - Upon every memory access
    - Excessive memory traffic
  - Upon a cache miss
    - Catches contiguous streams of data non-present in the cache
    - Requires a miss before prefetching is initiated
  - Tagged prefetch
    - One bit per cache block indicates if block was referenced
    - Bit set to zero if block was prefetched
    - Zero-to-one transition indicates access that would have been a miss if block were not prefetched and triggers lookahead prefetching

Stream Buffers



- Each buffer fetches data from one contiguous stream
- Cache and head entries of stream buffers checked upon access
- Cache miss may be served by head of stream buffer

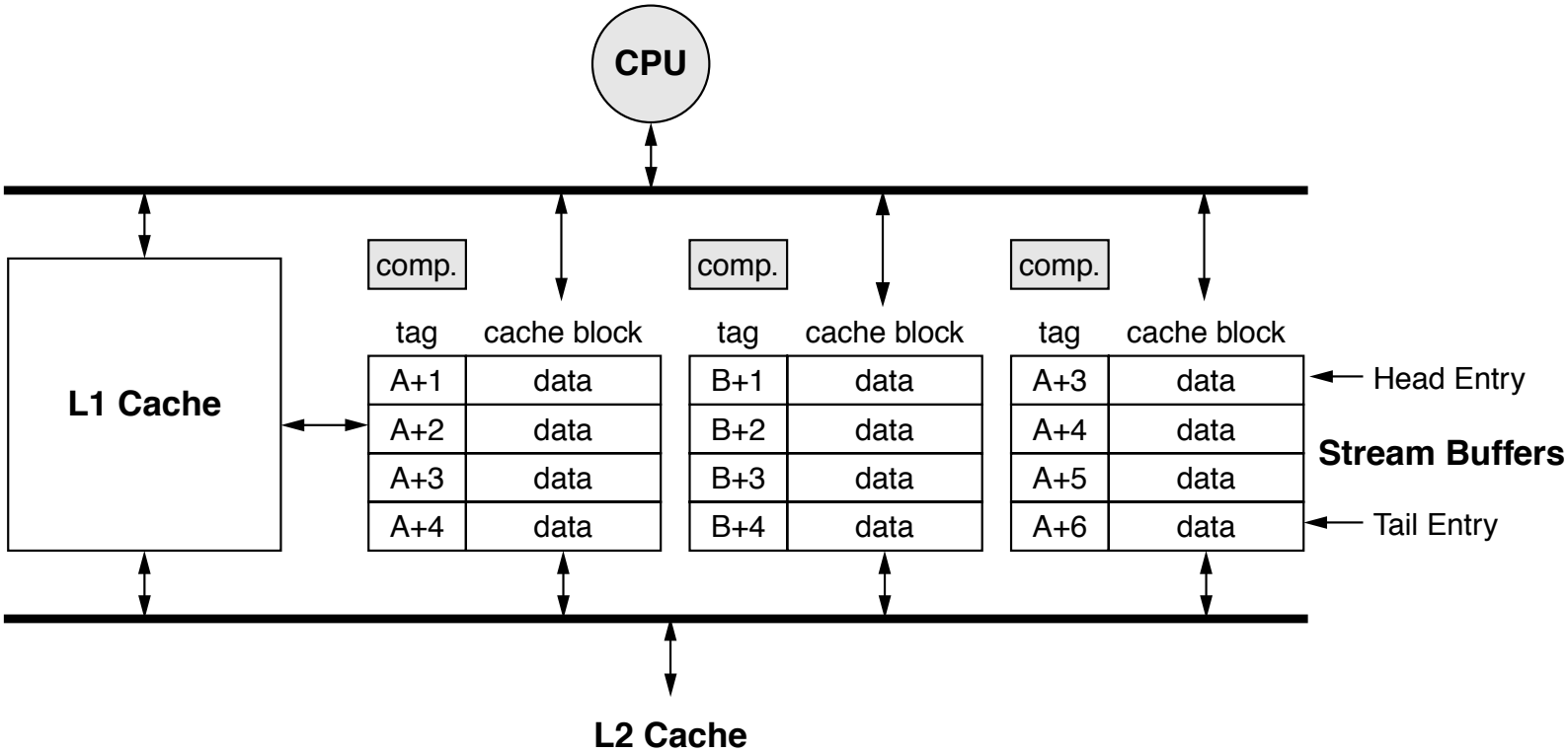
Stream Buffers



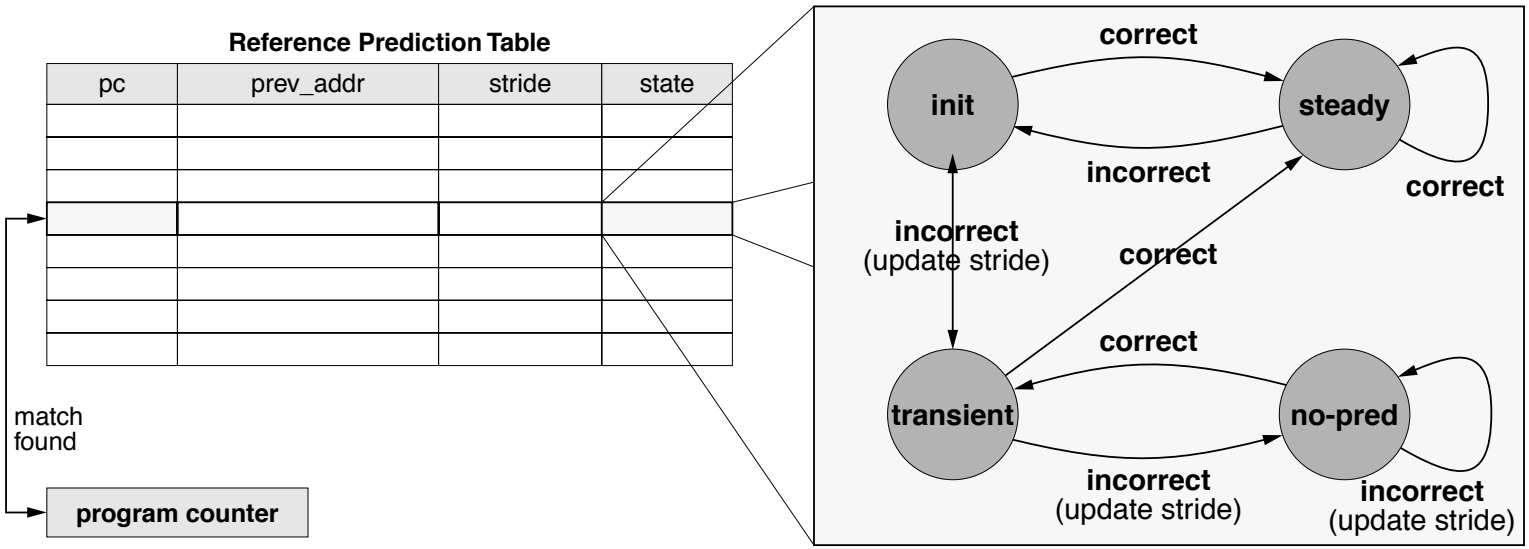
- If cache miss hits on stream buffer, head pointer moves down and prefetching is triggered
- Available bit per entry indicates if prefetching is in flight
- Buffer allocated when a stream of misses (e.g. address A, A+1,...) is detected

Strided Prefetching Motivation

- Assume the reference pattern: A, B, A+2, B+1, A+4, B+2,...
- Stream buffer space wasted in this case

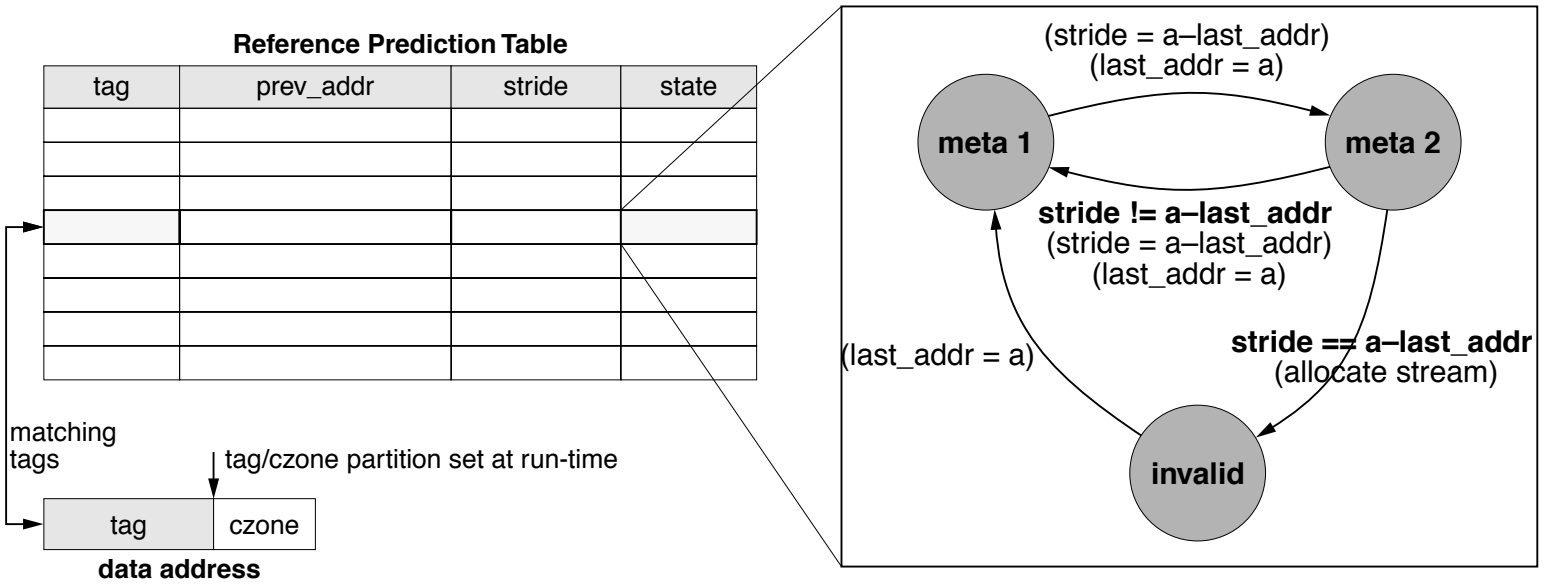


Strided Prefetching



- Reference prediction table tracks load/store accesses and strides between addresses of the same load/store
- Stride used to make prediction of next address to prefetch
- FSM tracks and fixes stride predictions

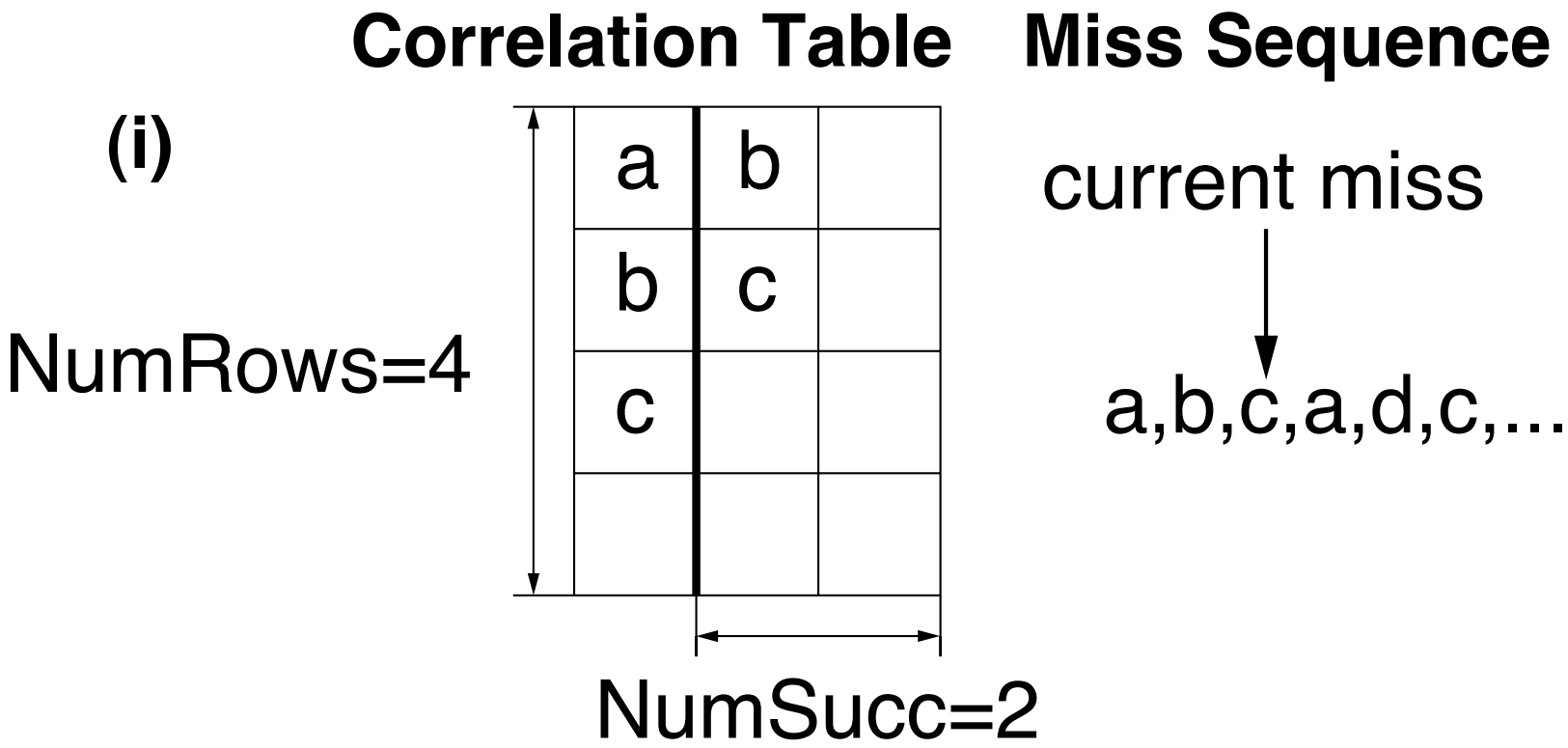
Strided prefetching without the Program Counter



- Tag partitions the address space in regions
- Prefetcher separates streams in different address regions
- FSM requires three references that miss

Correlation Prefetching

- Prefetching repeating patterns that are not dominated by a single or a few strides
- Algorithmic locality often not captured by strides (e.g. walking trees with dynamically allocated memory)



Correlation Prefetching

- Second Snapshot
- Successors of miss stored in MRU order
- Hardware keeps pointer to row of last observed miss
- On miss hardware updates successors and starts new correlation stream

(ii)

a	d	b
b	c	
c	a	
d	c	

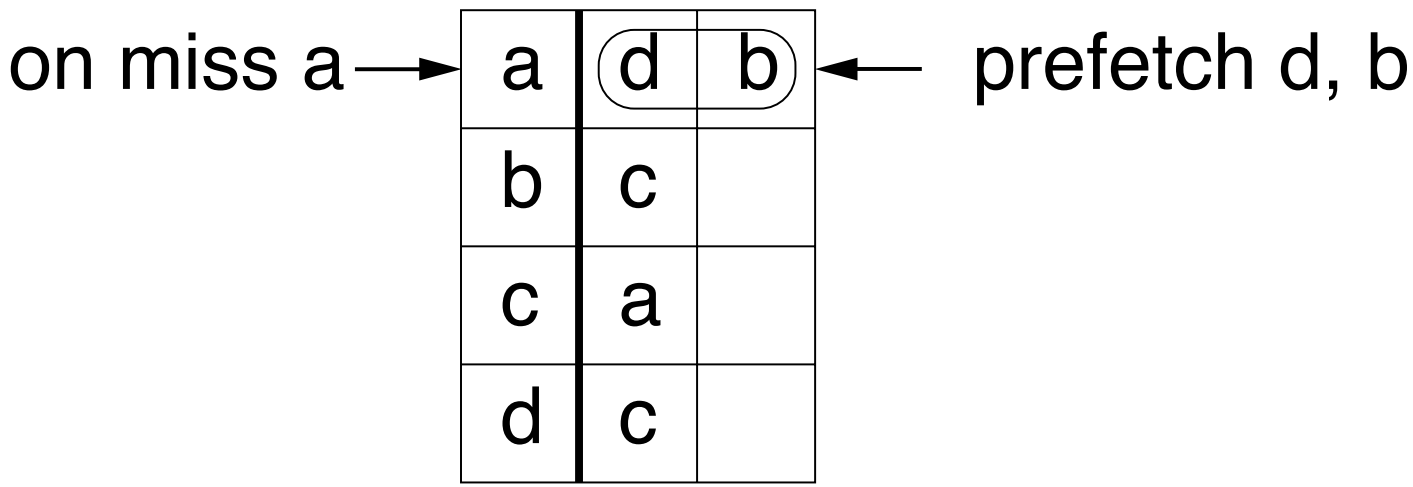
current miss

a,b,c,a,d,c,...

Correlation Prefetching

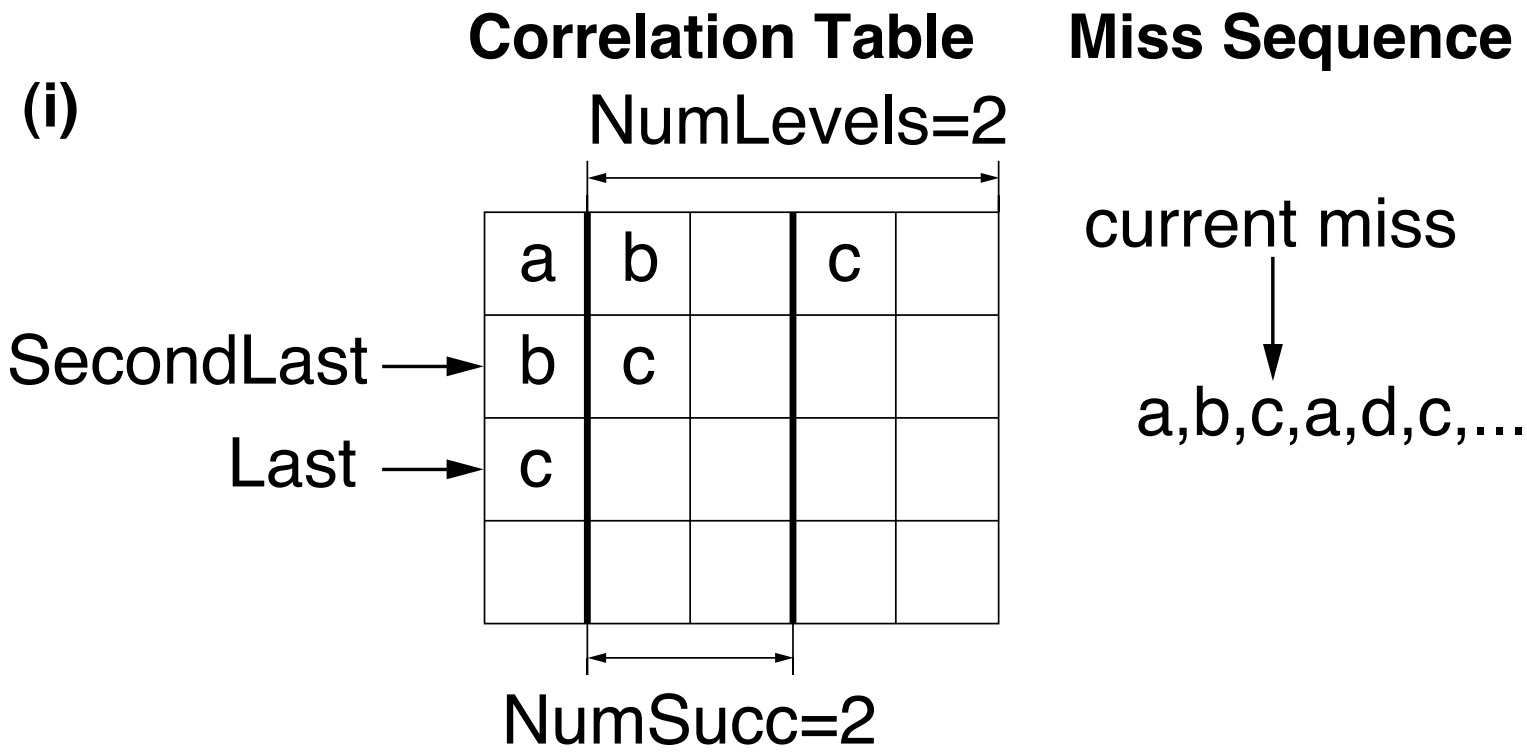
- Third Snapshot
- Only successors in single row prefeteched, limits performance

(iii)



Multi-level Correlation Prefetching

- Maintain multiple pointers (a queue) in the correlation table
- Replicate miss information in the table



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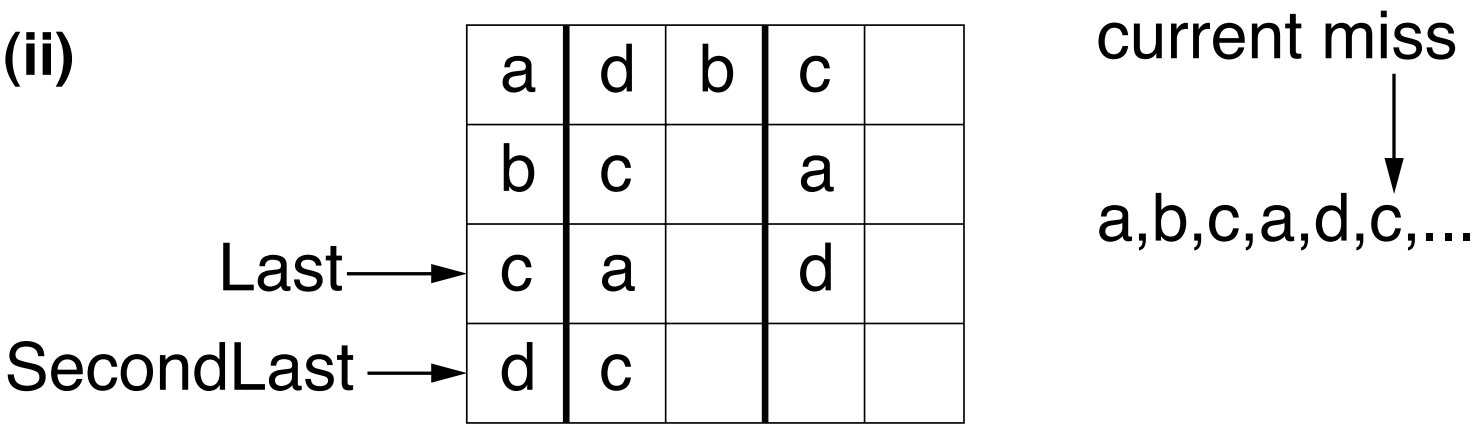
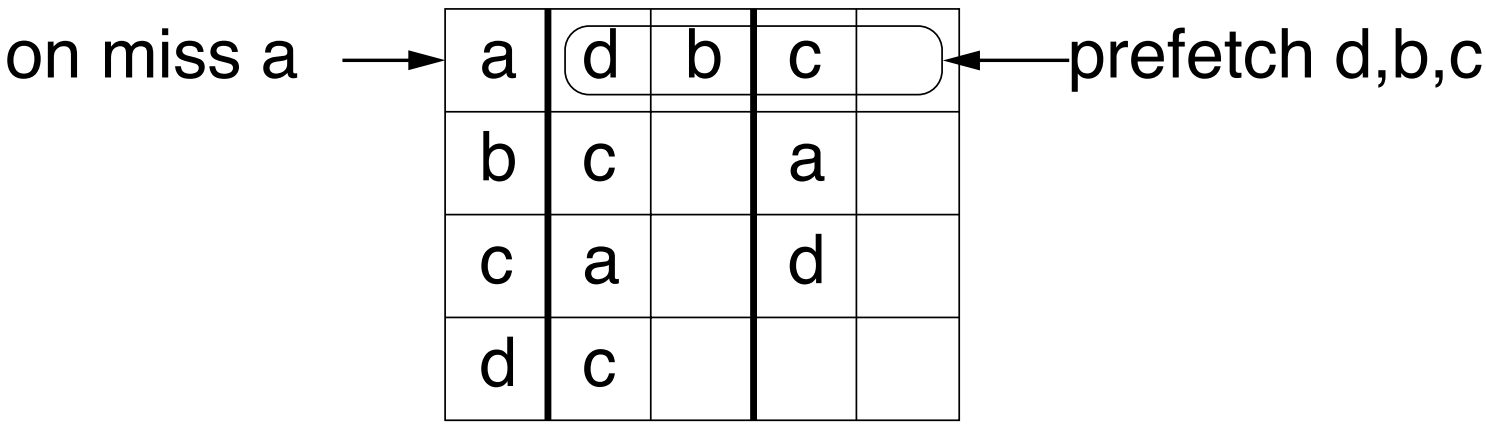


Multi-level Correlation Prefetching

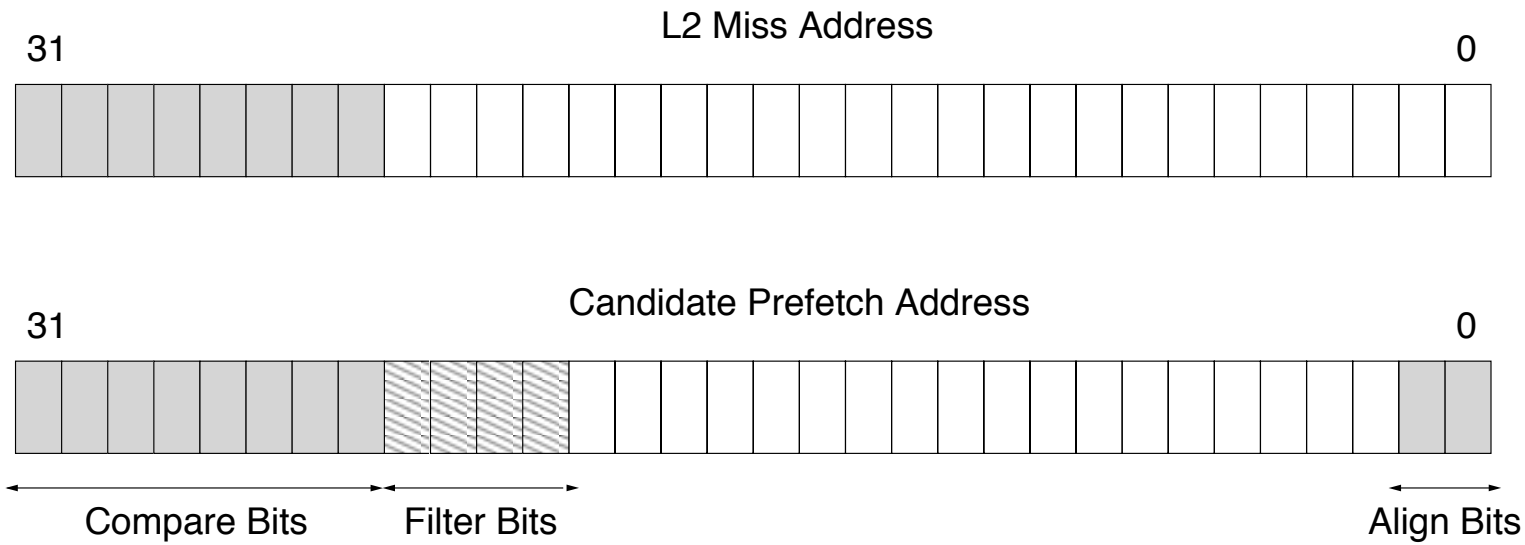
- Use NLEVELS-1 successors to index the table and prefetch more
- Example: NLEVELS=2

(iii)



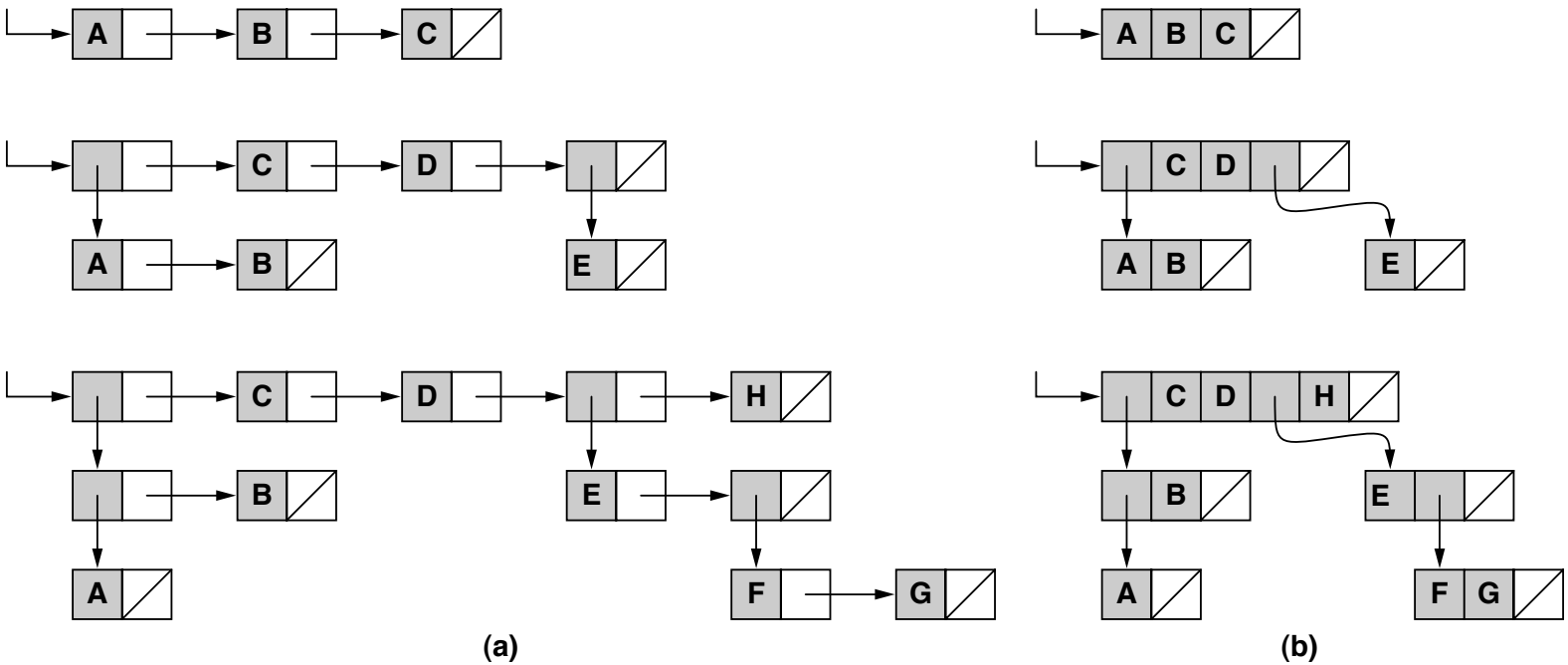
Other Prefetching Schemes

- Content-based prefetching
  - Identify two loads out of which one produces the address consumed by the other
  - Indicates pointer chasing
- Content-directed prefetching
  - Scan words fetched from memory to speculate if they are likely addresses
  - Prefetch if word fetched is an address

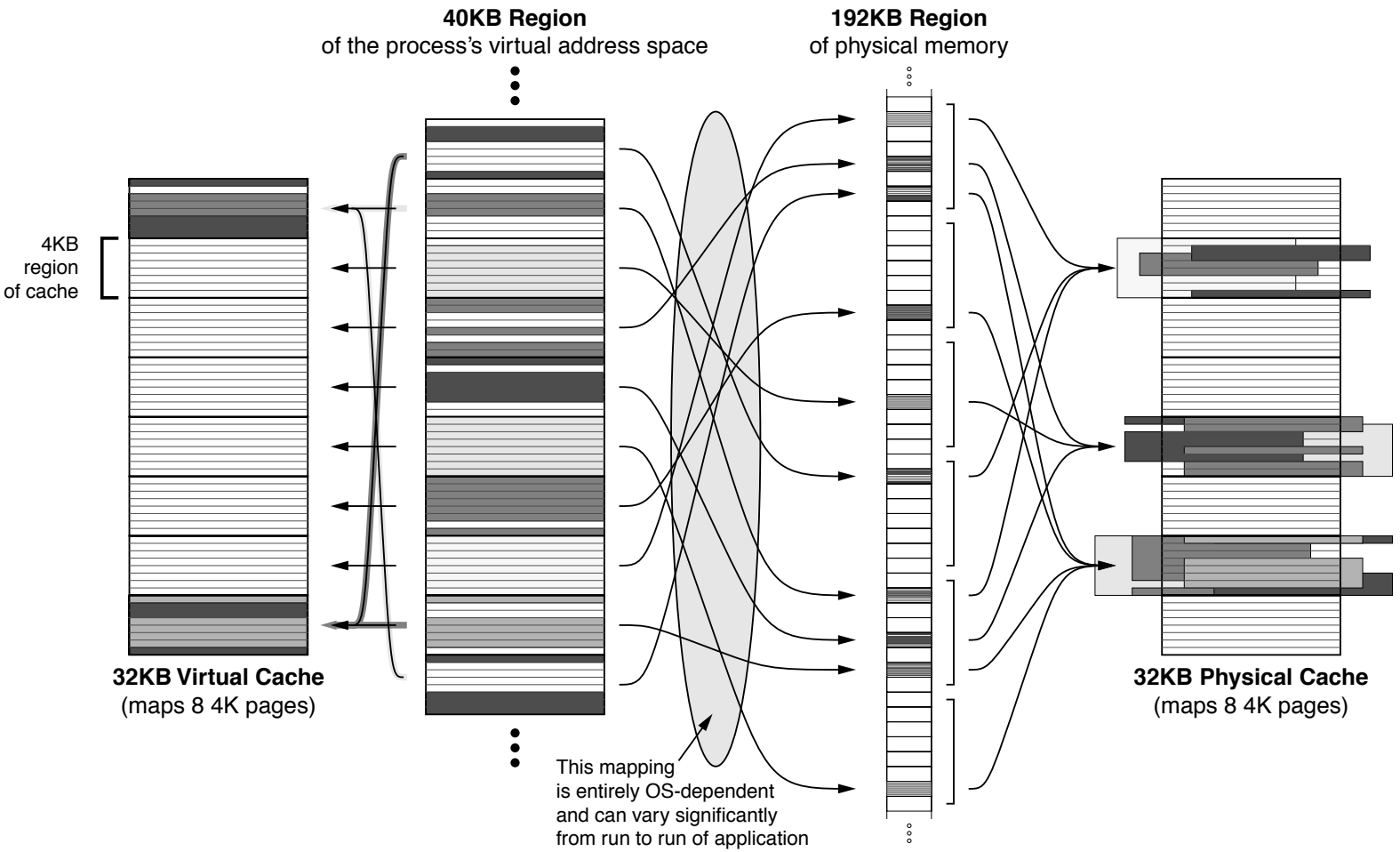


Dynamic Data Structure Reorganization for Locality

- List linearization
- Idea borrowed from garbage collection



Page Coloring



Page Coloring

- Physical layout of pages of data in DRAM differs from physical layout of pages of data in cache
- Consequence of virtual-to-physical address translation
- Software can implement conflict-free placement of pages if cache is virtually-indexed
  - Placing working set in adjacent virtual pages guarantees mapping in adjacent cache page-size regions
- Page coloring
  - Match bottom bits of virtual page number with bottom bits of physical frame number
  - Implemented using bins of physical pages that map to the same page-size region in the cache
  - Implementation lies in the operating system

Software Prefetching

Mowry's algorithm:

- Identify statically references that miss using locality analysis
- Examples assumes array elements are doubles and cache block is 32 bytes

```
a) for (j=2; j <= N-1; j++)
     for (i=2; i <= N-1; i++)
       A[j][i]=0.25*(B[j][i-1]+B[j][i+1]+B[j-1][i]+B[j+1][i]);


b) for (j=2; j <= N-1; j++) {
     for (i=2; i <= PD; i+=4) {      //   Prologue
       prefetch(&B[j][i]);
       prefetch(&B[j-1][i]);
       prefetch(&B[j+1][i]);
       prefetch(&A[j][i]);
     }
     for (i=2; i < N-PD-1; i+=4) {   //   Steady State
       prefetch(&B[j][i+PD]);
       prefetch(&B[j-1][i+PD]);
       prefetch(&B[j+1][i+PD]);
       prefetch(&A[j][i+PD]);

       A[j][i]=0.25*(B[j][i-1]+B[j][i+1]+B[j-1][i]+B[j+1][i]);
       A[j][i+1]=0.25*(B[j][i]+B[j][i+2]+B[j-1][i+1]+B[j+1][i+1]);
       A[j][i+2]=0.25*(B[j][i+1]+B[j][i+3]+B[j-1][i+2]+B[j+1][i+2]);
       A[j][i+3]=0.25*(B[j][i+2]+B[j][i+4]+B[j-1][i+3]+B[j+1][i+3]);
     }
     for (i=N-PD; i <= N-1; i++)     //   Epilogue
       A[j][i]=0.25*(B[j][i-1]+B[j][i+1]+B[j-1][i]+B[j+1][i]);
   }
```

Software Prefetching

Mowry's algorithm:

- Algorithm identifies spatial reuse (all references in example), temporal reuse for each reference and temporal reuse for group of references
- Algorithm computes number of iterations between reuses and volume of data accessed to identify misses

```
a) for (j=2; j <= N-1; j++)
     for (i=2; i <= N-1; i++)
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       prefetch(&B[j][i]);
       prefetch(&B[j-1][i]);
       prefetch(&B[j+1][i]);
       prefetch(&A[j][i]);
     }
     for (i=2; i < N-PD-1; i+=4) {   //   Steady State
       prefetch(&B[j][i+PD]);
       prefetch(&B[j-1][i+PD]);
       prefetch(&B[j+1][i+PD]);
       prefetch(&A[j][i+PD]);

       A[j][i]=0.25*(B[j][i-1]+B[j][i+1]+B[j-1][i]+B[j+1][i]);
       A[j][i+1]=0.25*(B[j][i]+B[j][i+2]+B[j-1][i+1]+B[j+1][i+1]);
       A[j][i+2]=0.25*(B[j][i+1]+B[j][i+3]+B[j-1][i+2]+B[j+1][i+2]);
       A[j][i+3]=0.25*(B[j][i+2]+B[j][i+4]+B[j-1][i+3]+B[j+1][i+3]);
     }
     for (i=N-PD; i <= N-1; i++)     //   Epilogue
       A[j][i]=0.25*(B[j][i-1]+B[j][i+1]+B[j-1][i]+B[j+1][i]);
   }
```

Software Prefetching

Mowry's algorithm:

- Loop unrolling and peeling isolate cache misses (one per reference per unrolled iteration in example)
- Compiler inserts prefetches for references that miss using a prefetch distance, measured in iterations

```
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     }
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       A[j][i+3]=0.25*(B[j][i+2]+B[j][i+4]+B[j-1][i+3]+B[j+1][i+3]);
     }
     for (i=N-PD; i <= N-1; i++)     //   Epilogue
       A[j][i]=0.25*(B[j][i-1]+B[j][i+1]+B[j-1][i]+B[j+1][i]);
   }
```

Pointer Prefetching

Pointer chasing:

a)
```
struct node {data, next}
  *ptr, *list_head;

ptr = list_head;
while (ptr) {
  prefetch(ptr->next);
  ...
  ptr = ptr->next;
}
```

b)
```
struct node {data, left, right}
  *ptr;

void recurse(ptr){
  prefetch(ptr->left);
  prefetch(ptr->right);
  ...
  recurse(ptr->left);
  recurse(ptr->right);
}
```

Pointer Prefetching

Prefetching using jump pointers:

a)
```
struct node {data, next, jump}
  *ptr, *list_head, *prefetch_array[PD], *history[PD];
int i, head, tail;

for (i = 0; i < PD; i++) //    Prologue Loop
  prefetch(prefetch_array[i]);

ptr = list_head;
while (ptr->next) {  //   Steady State Loop
  prefetch(ptr->jump);
  ...
  ptr = ptr->next;
}
```

b)
```
for (i = 0; i < PD; i++) history[i] = NULL;
tail = 0;
head = PD-1;

ptr = list_head;
while (ptr) {  //    Prefetch Pointer Generation Loop
  history[head] = ptr;
  if (!history[tail])
    prefetch_array[tail] = ptr;
  else
    history[tail]->jump = ptr;
  head = (head+1)%PD;
  tail = (tail+1)%PD;
  ptr = ptr->next;
}
```